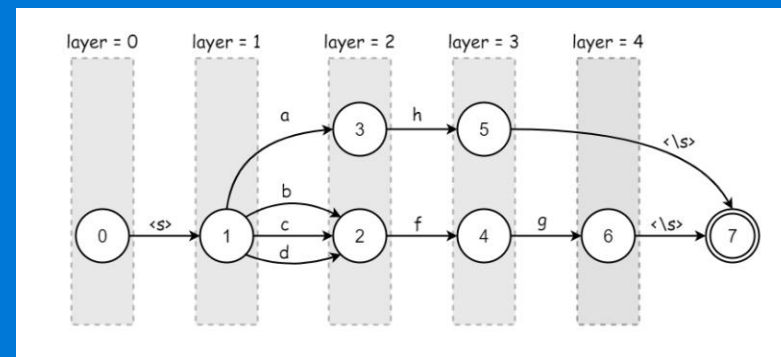


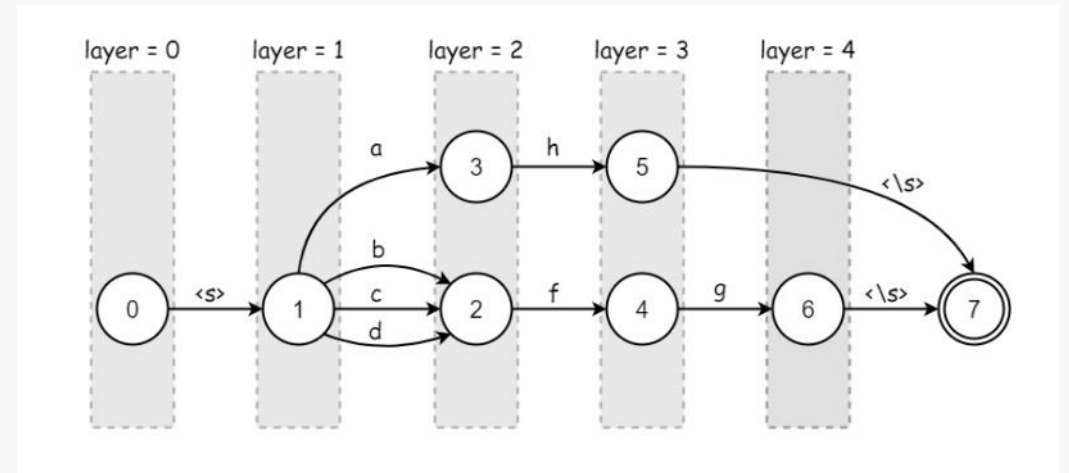
# A GPU-based WFST Decoder with Exact Lattice Generation

Zhehuai Chen, Justin Luitjens, Hainan Xu, Yiming Wang,  
Daniel Povey, Sanjeev Khudanpur



# Outline

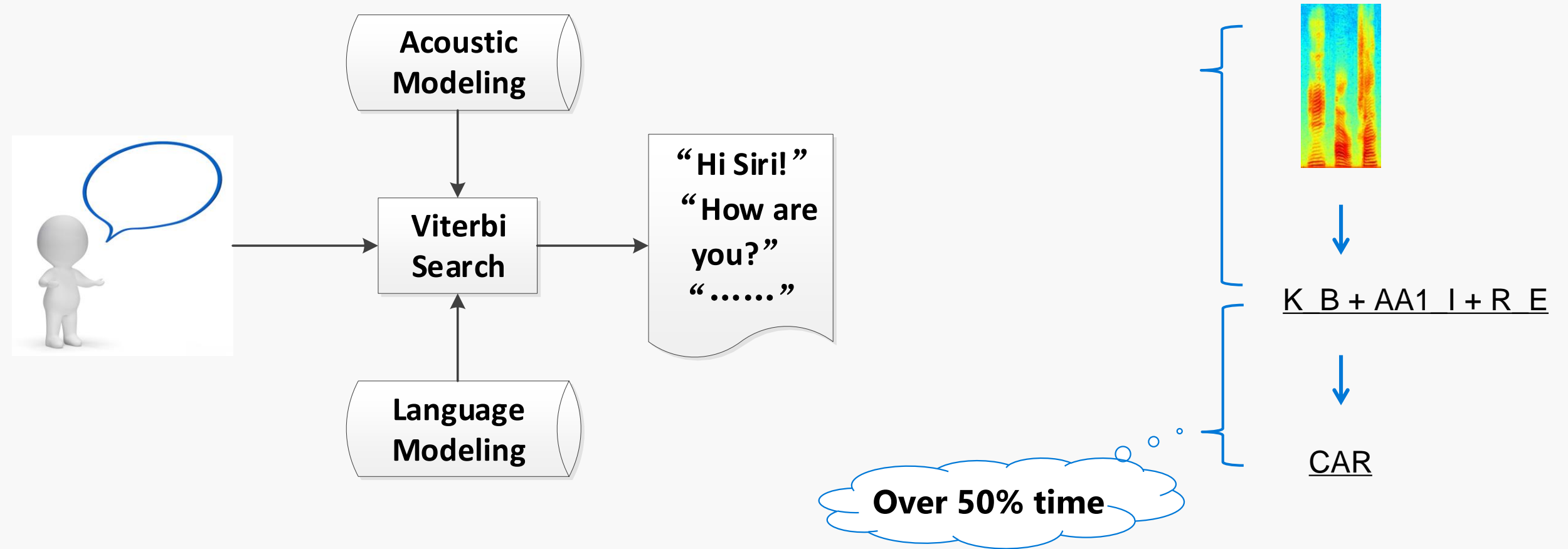
- Introduction
  - ASR and WFST Decoding
  - GPU-based Parallel Computing
- Parallel Viterbi Decoding<sup>1</sup>
  - Framework
  - Token Recombination
  - Load Balancing
  - Lattice Processing
- Experiments



1. <https://github.com/chenzhehuai/kaldi/tree/gpu-decoder>

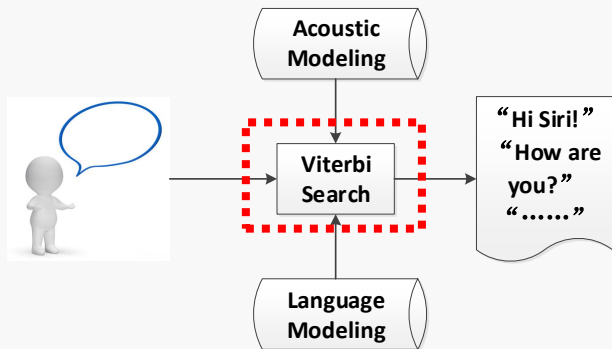
# Introduction

- Automatic Speech Recognition (ASR)

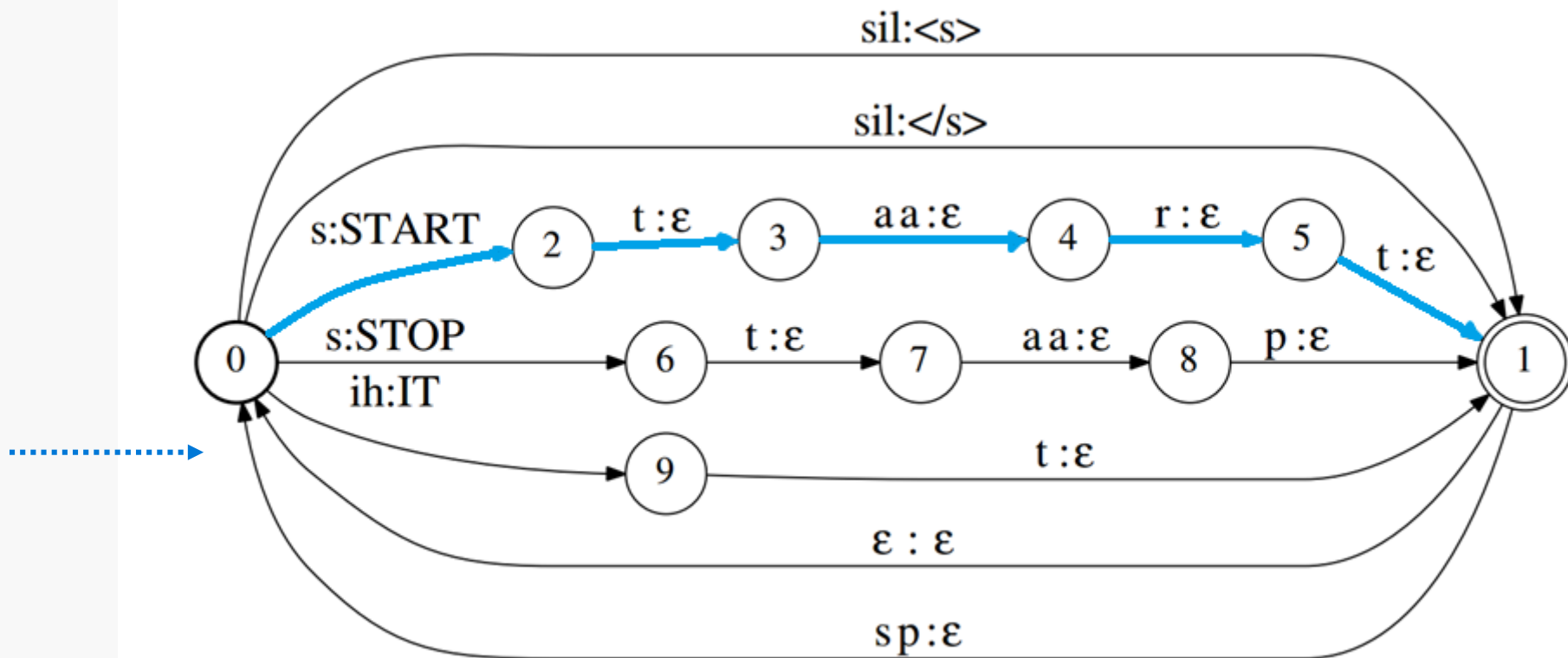


# Introduction

- Weighted finite state transducer (WFST) Decoding



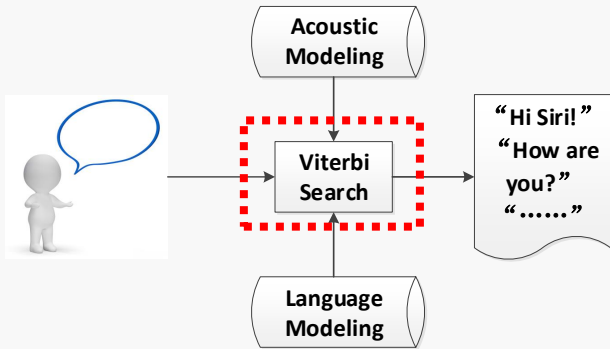
word	Pronunciation	Score <sup>1</sup>
<s>	sil	0.1
</s>	sil	0.6
START	s t aa r t	0.5
STOP	s t aa p	0.4
IT	ih t	0.3



1. There is a score for each arc. For simplicity, we do not draw them.

# Introduction

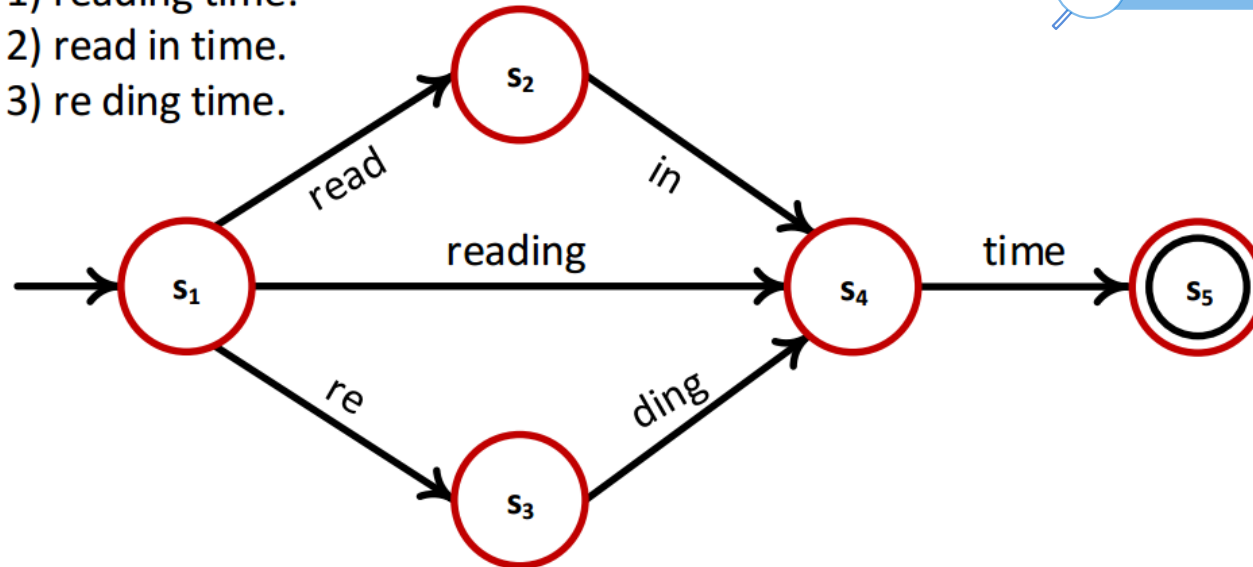
- Lattice Processing



- Lattice rescoring
- Discriminative training
- Confidence measure
- Confusion network
- etc.

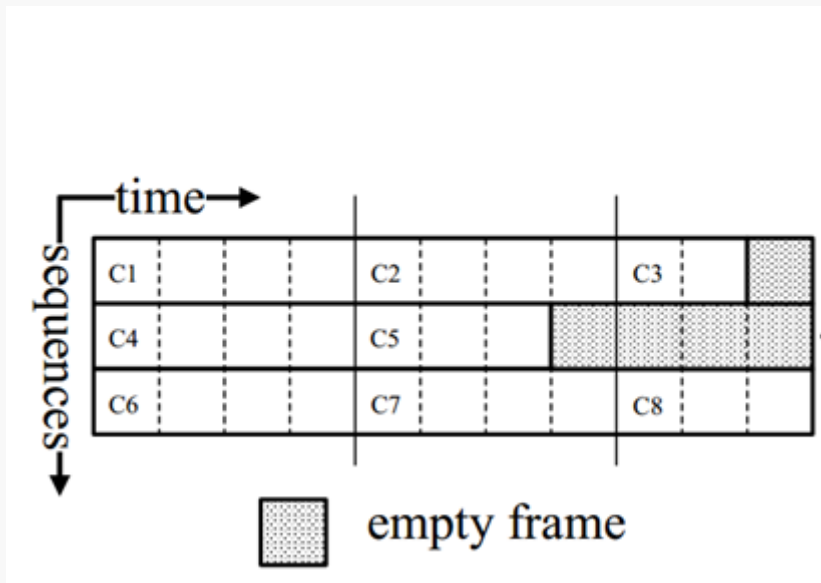
## N-best hypotheses:

- 1) reading time.
- 2) read in time.
- 3) re ding time.

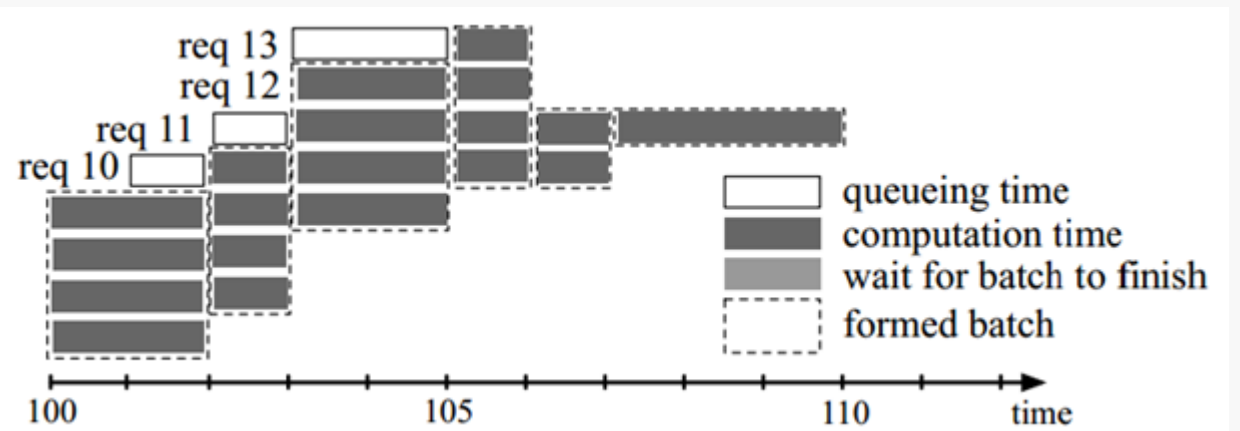


# Introduction

- GPU-based Parallel Computing
  - Matrix calculation
  - Sequence batching



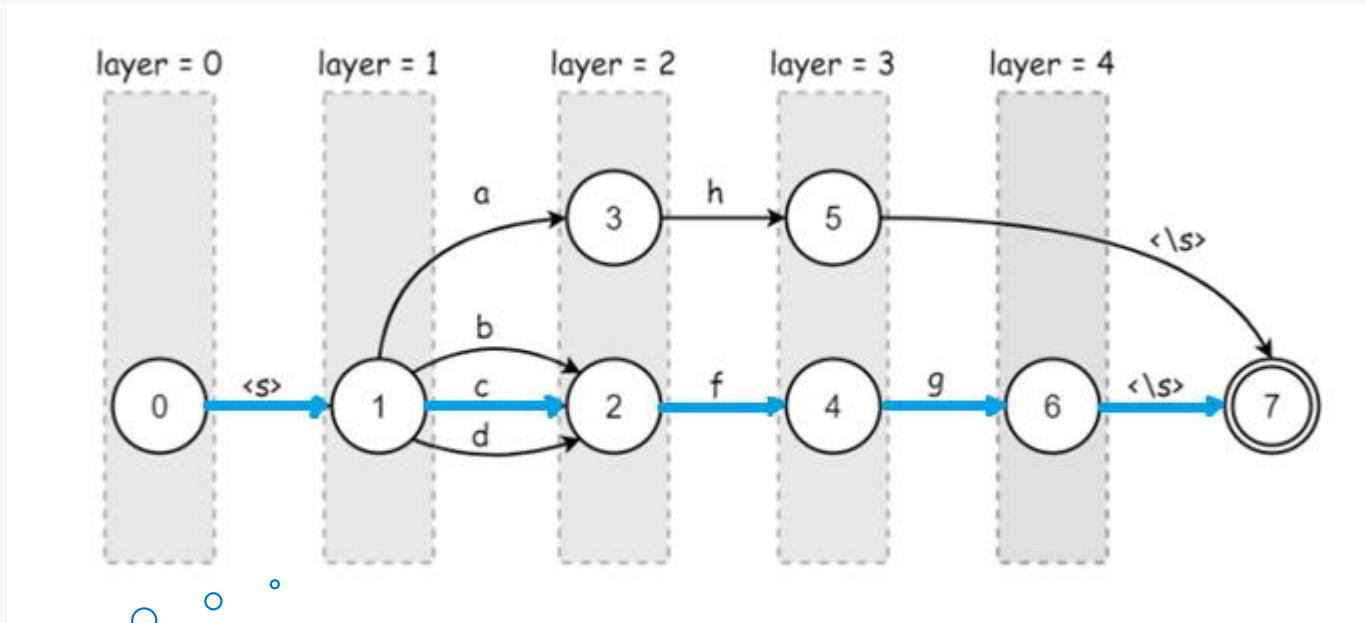
**Training**



**Inference**

# Introduction

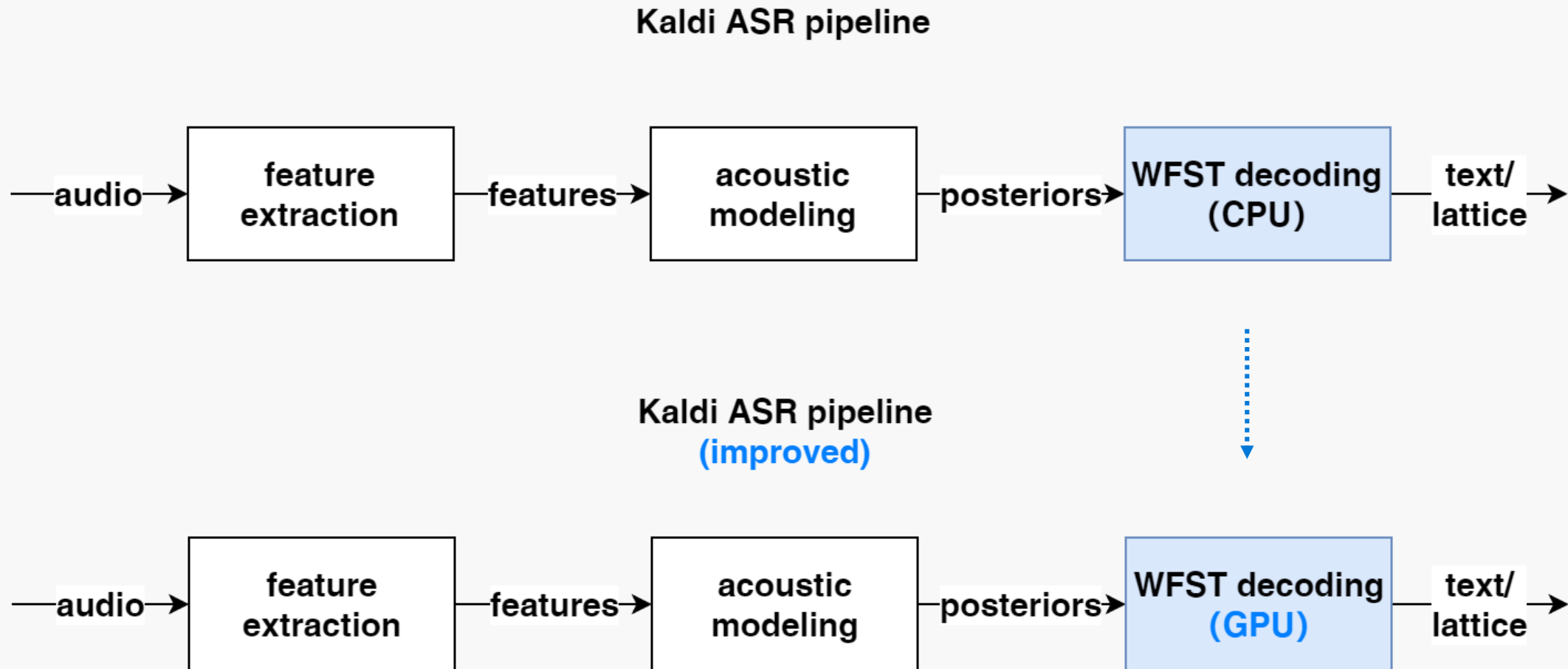
- This Work: GPU-based Decoding



**Parallel** Viterbi Search

# Introduction

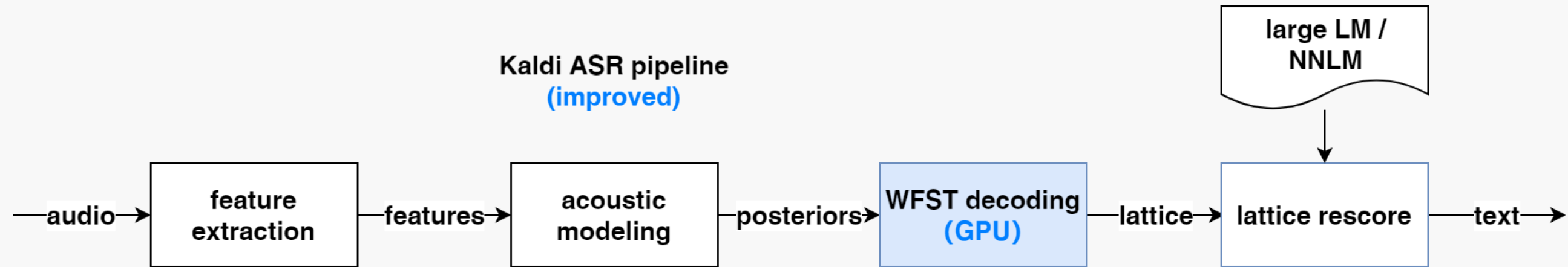
- This Work: **GPU-based Decoding**





# Introduction

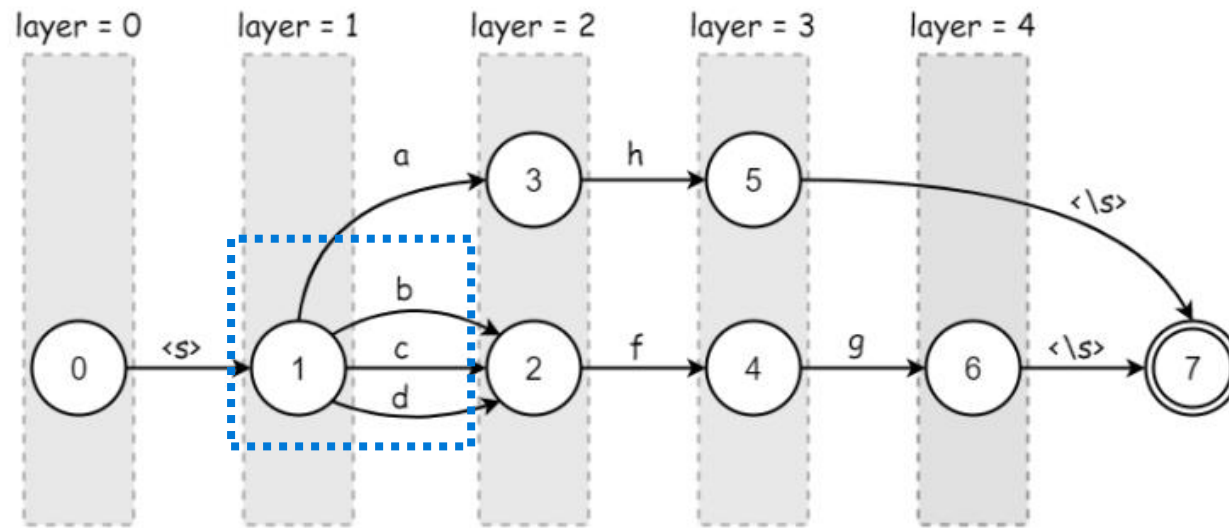
- This Work: GPU-based Decoding



- GPU memory is enough for 1-pass WFST

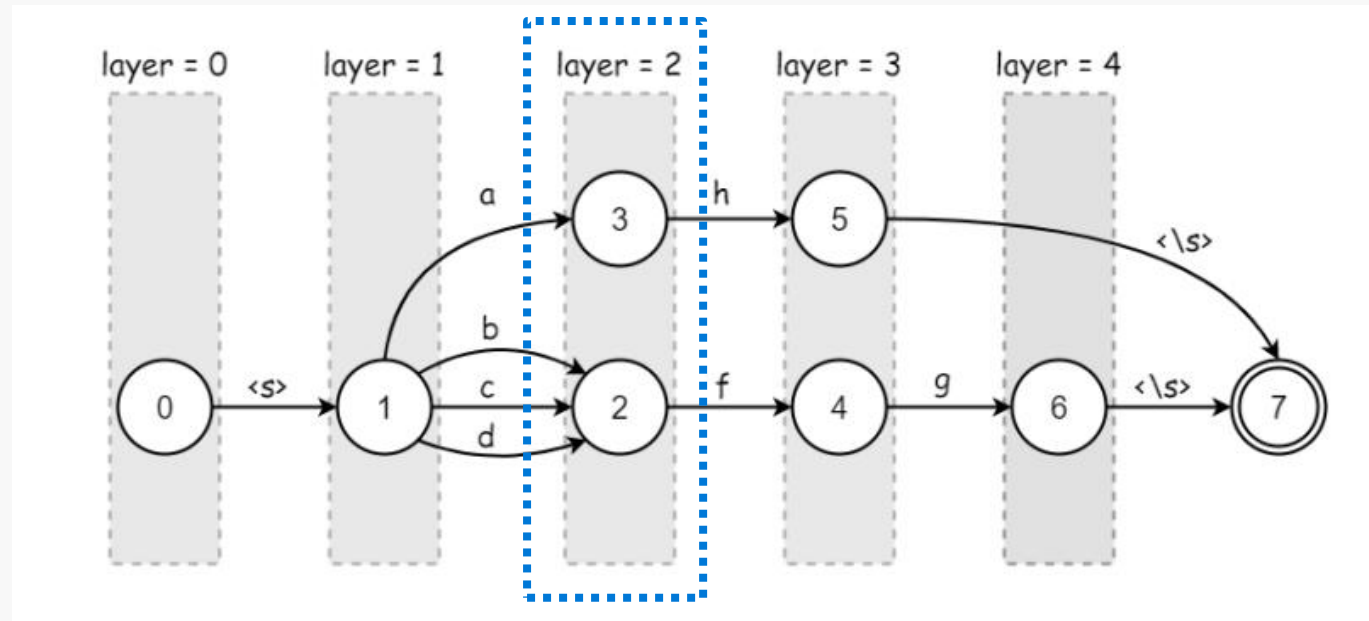
# Framework

- **Parallel** Viterbi decoding
  - **Future:** out-going arcs, e.g. b, c & d



# Framework

- **Parallel** Viterbi decoding
  - **Future:** out-going arcs, e.g. b, c & d
  - **History:** per layer, e.g. 3 & 2



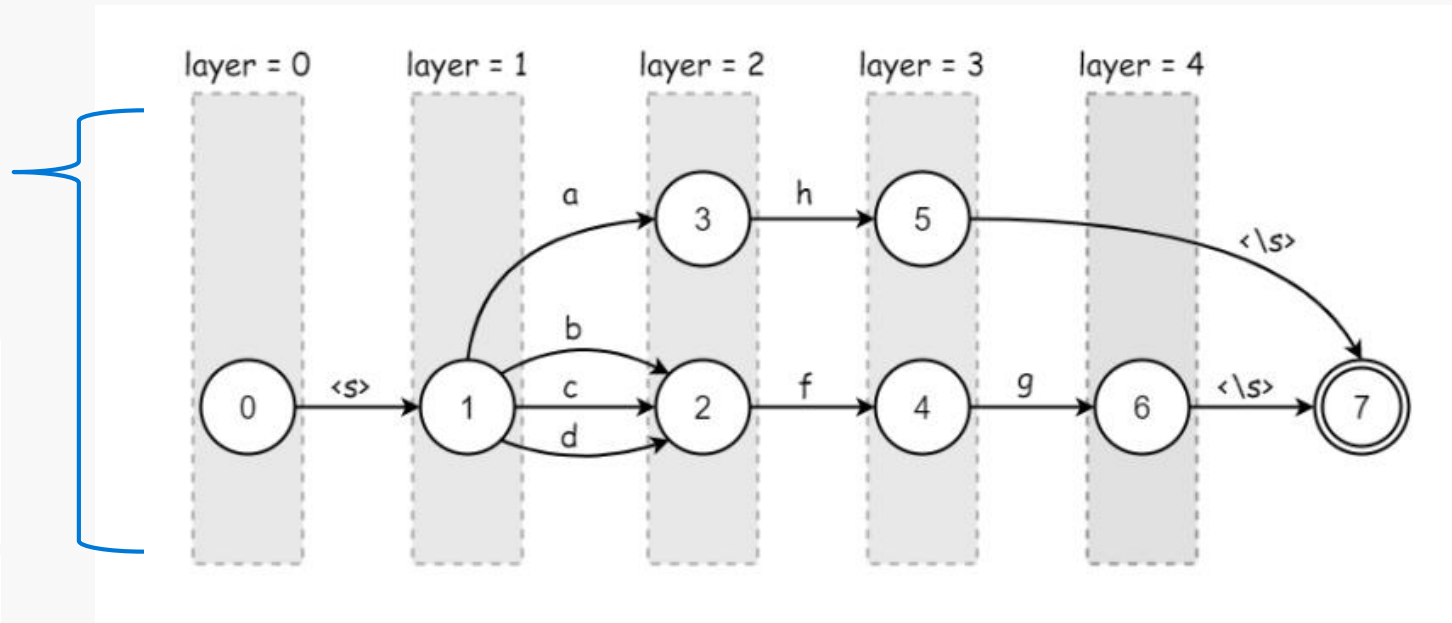
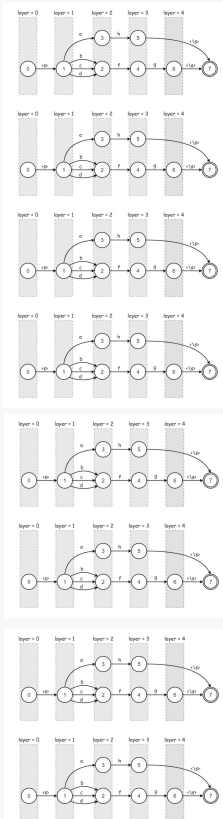
# Framework

- **Parallel** Viterbi decoding

- **Future:** out-going arcs, e.g. b, c & d

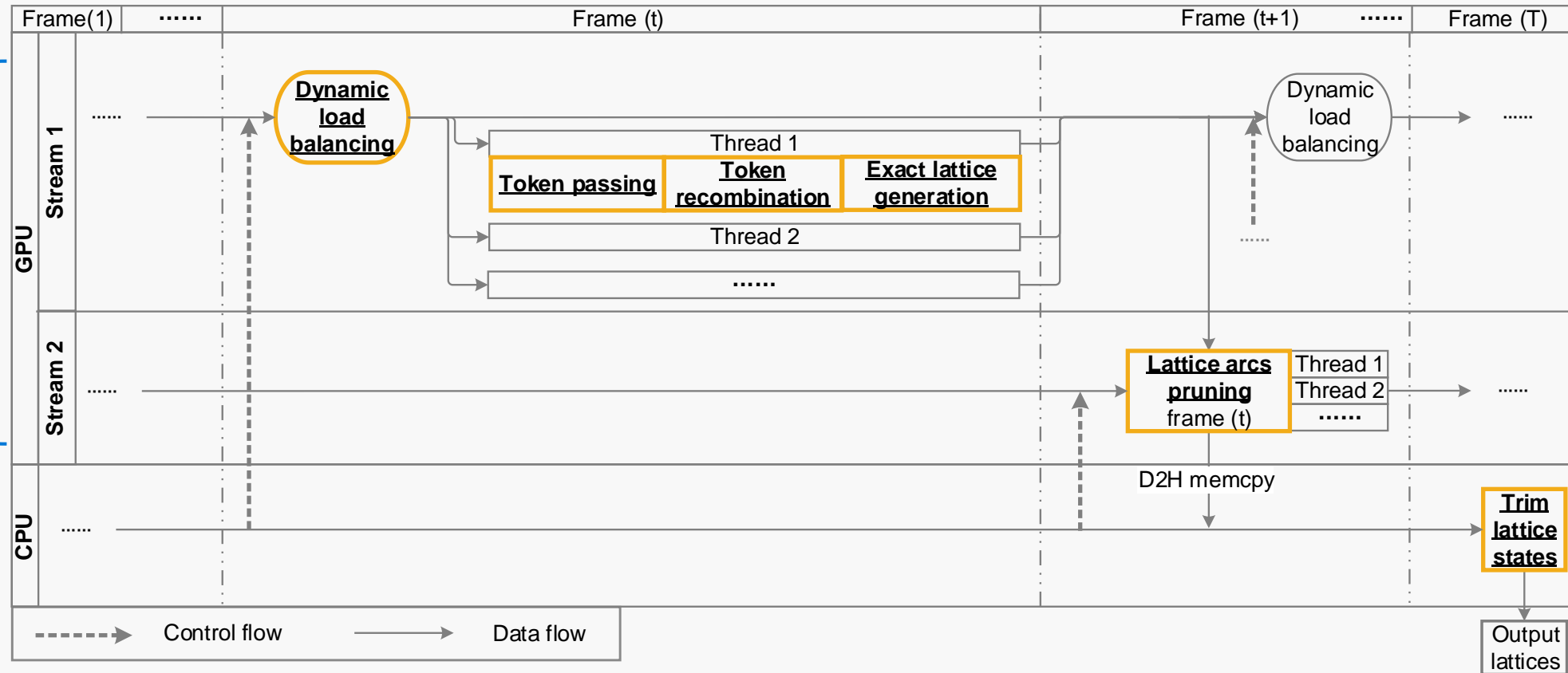
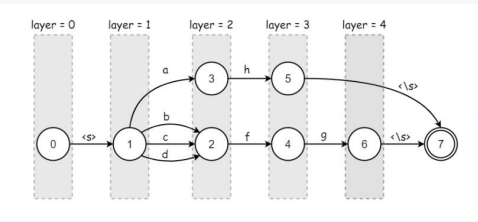
- **History:** per layer, e.g. 3 & 2

- **Utterance:** decoding with separate GPU kernels



# Framework

- System overview
  - 2 GPU streams & 1 CPU thread



# 1<sup>st</sup> Problem: Token recombination

- Token recombination

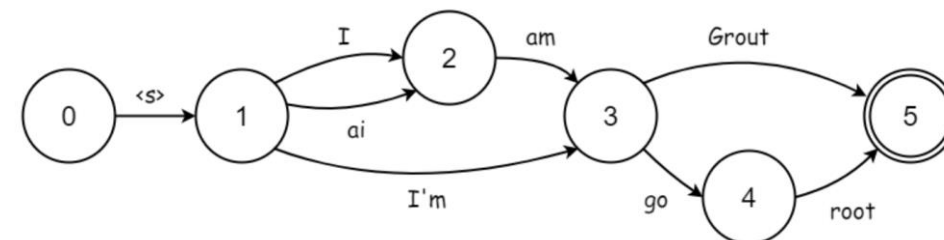
Language Model

Dictionary

DNN-HMM

$$\max P(\mathbf{W}|\mathbf{O}) \propto \max P(\mathbf{W}) \cdot P(\mathbf{L}|\mathbf{W}) \cdot \sum_{\mathbf{q} \in \mathcal{A}(\mathbf{L})} p(\mathbf{O}, \mathbf{q}|\mathbf{L}) \quad (1)$$

$$\propto \max P(\mathbf{W}) \cdot P(\mathbf{L}|\mathbf{W}) \cdot \max_{\mathbf{q} \in \mathcal{A}(\mathbf{L})} p(\mathbf{O}, \mathbf{q}|\mathbf{L}) \quad (2)$$



# Token recombination

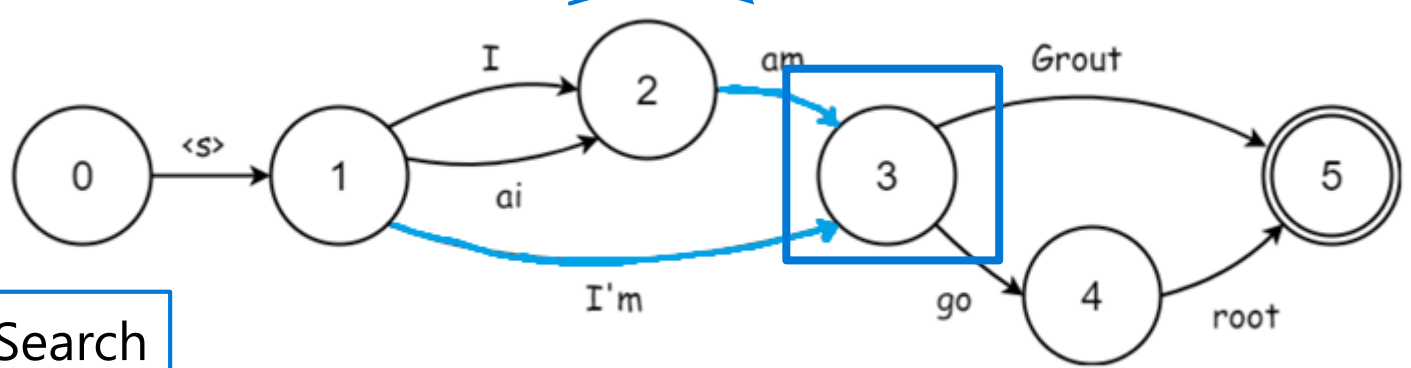
- Token recombination

$$\max P(\mathbf{W}|\mathbf{O}) \propto \max P(\mathbf{W}) \cdot P(\mathbf{L}|\mathbf{W}) \cdot \max_{\mathbf{q} \in \mathcal{A}(\mathbf{L})} p(\mathbf{O}, \mathbf{q}|\mathbf{L}) \quad (2)$$

**Serial** Viterbi Search

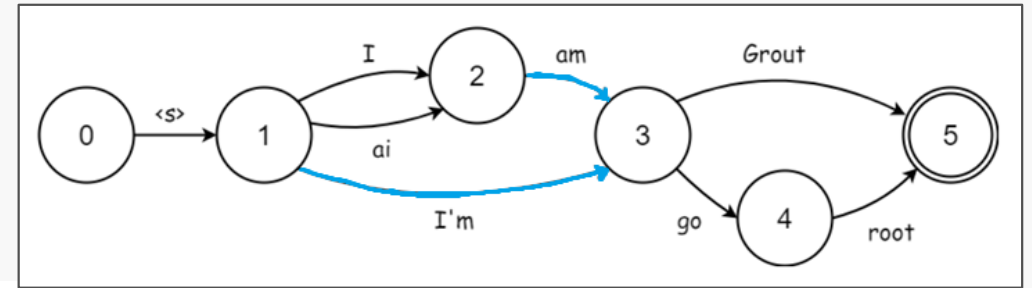
**Parallel** Viterbi Search

We need a **Thread Sync.**



# Token recombination

- Naïve implementation:
  - Critical section



```
1 while(*cur_tokv < next_tok) { // check if we need to recombine token
2   acquire_semaphore[(int*)&params.token_locks[nextstate]]; // per token lock
3   if(*cur_tokv < next_tok) { // double check if we are min
4     *cur_tok=next_tok; // this is what we really want to do
5   }
6   release_semaphore[(int*)&params.token_locks[nextstate]]; // release per token lock
7   break; // exit loop as our update is done
8 } // end while
```

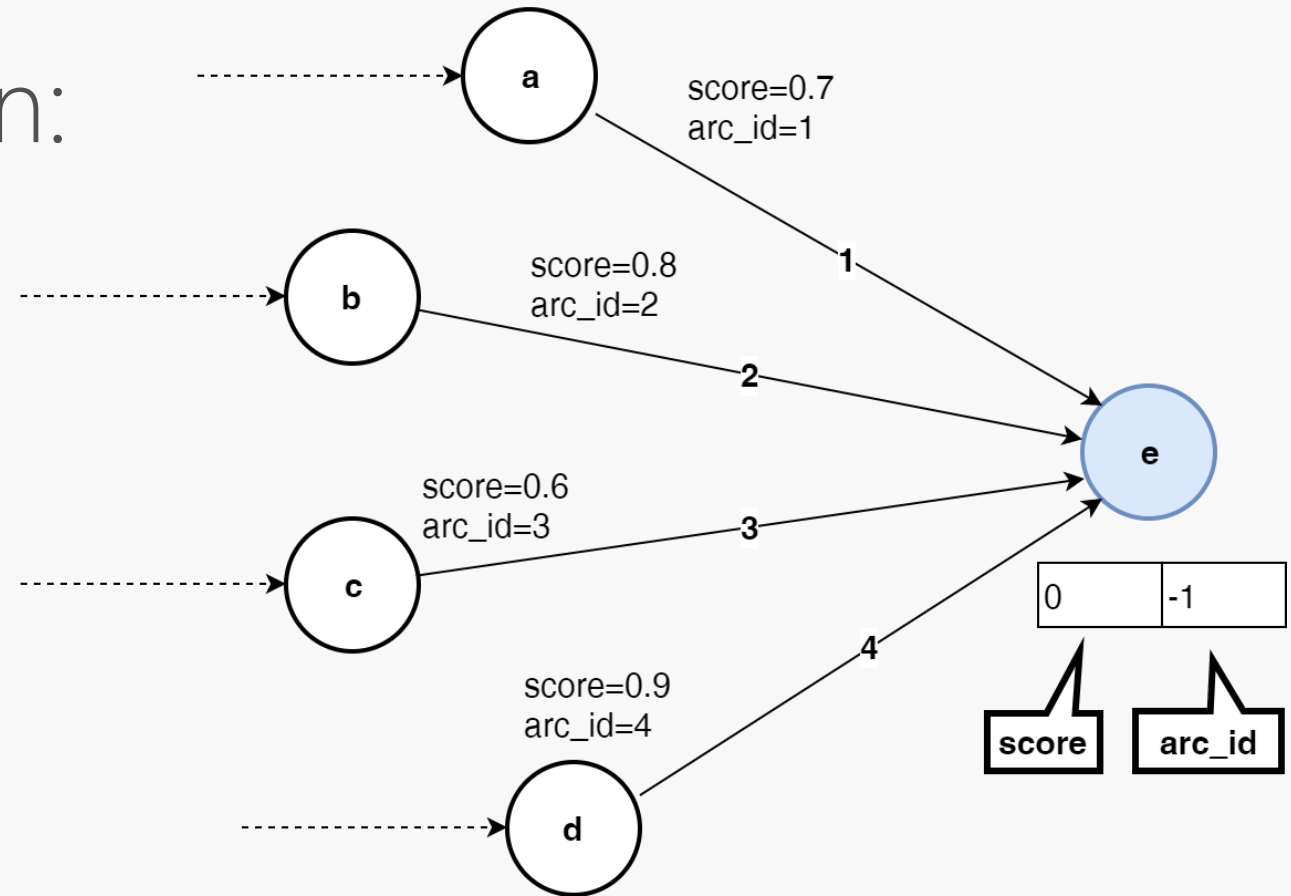
- Thread deadlock in earlier GPU architectures
- Slow because of **while loop** and **semaphore acquiring**



# Token recombination

- Proposed implementation:
  - Single atomic operation<sup>1</sup>

```
int64* atomicMax(*address, val) {  
    original = *address;  
    *address = max(val, *address);  
    return original;  
}
```

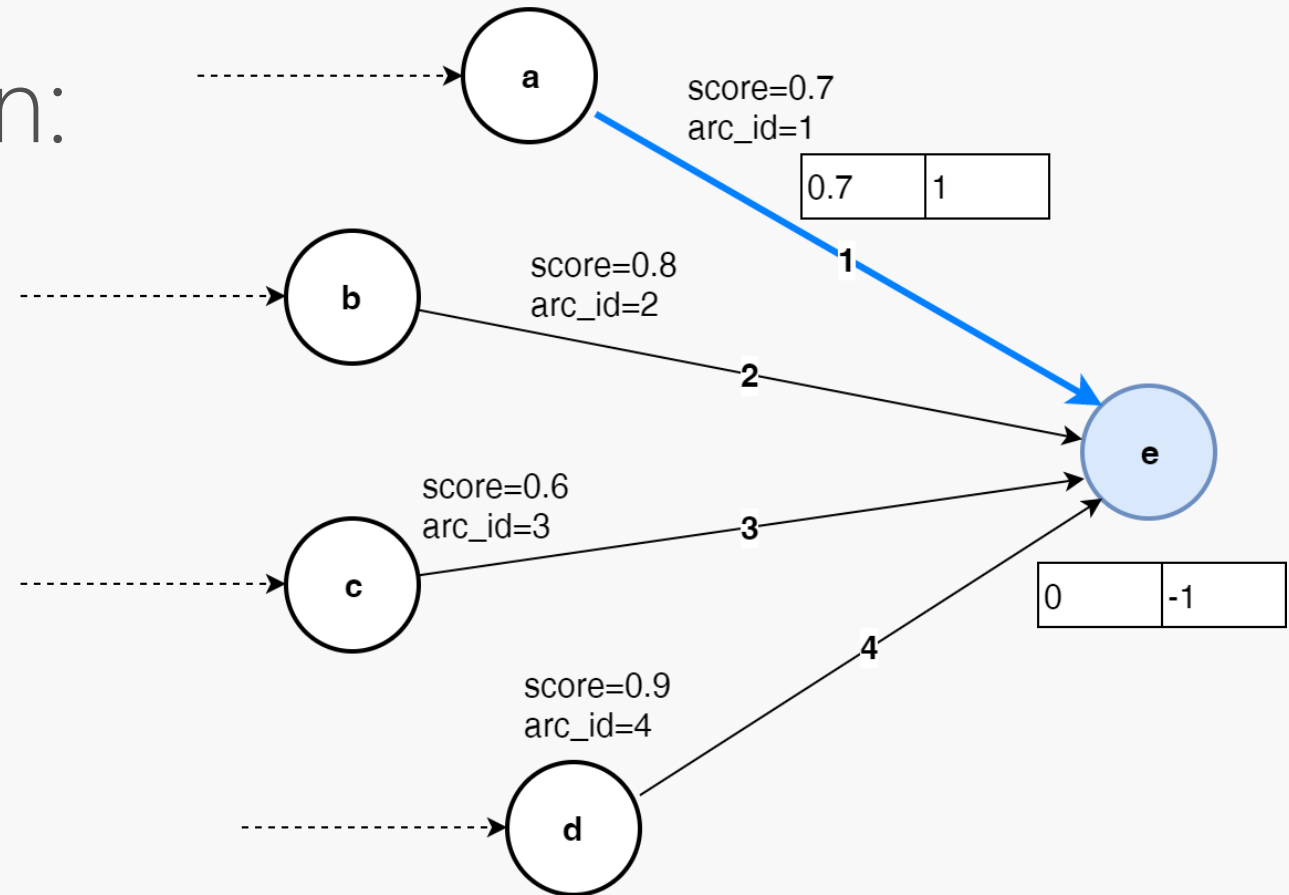


1. *atomicMax(\*address, val)*. Computes  $\max(*address, val)$ , writes the result to *address*, and returns the original *\*address*.

# Token recombination

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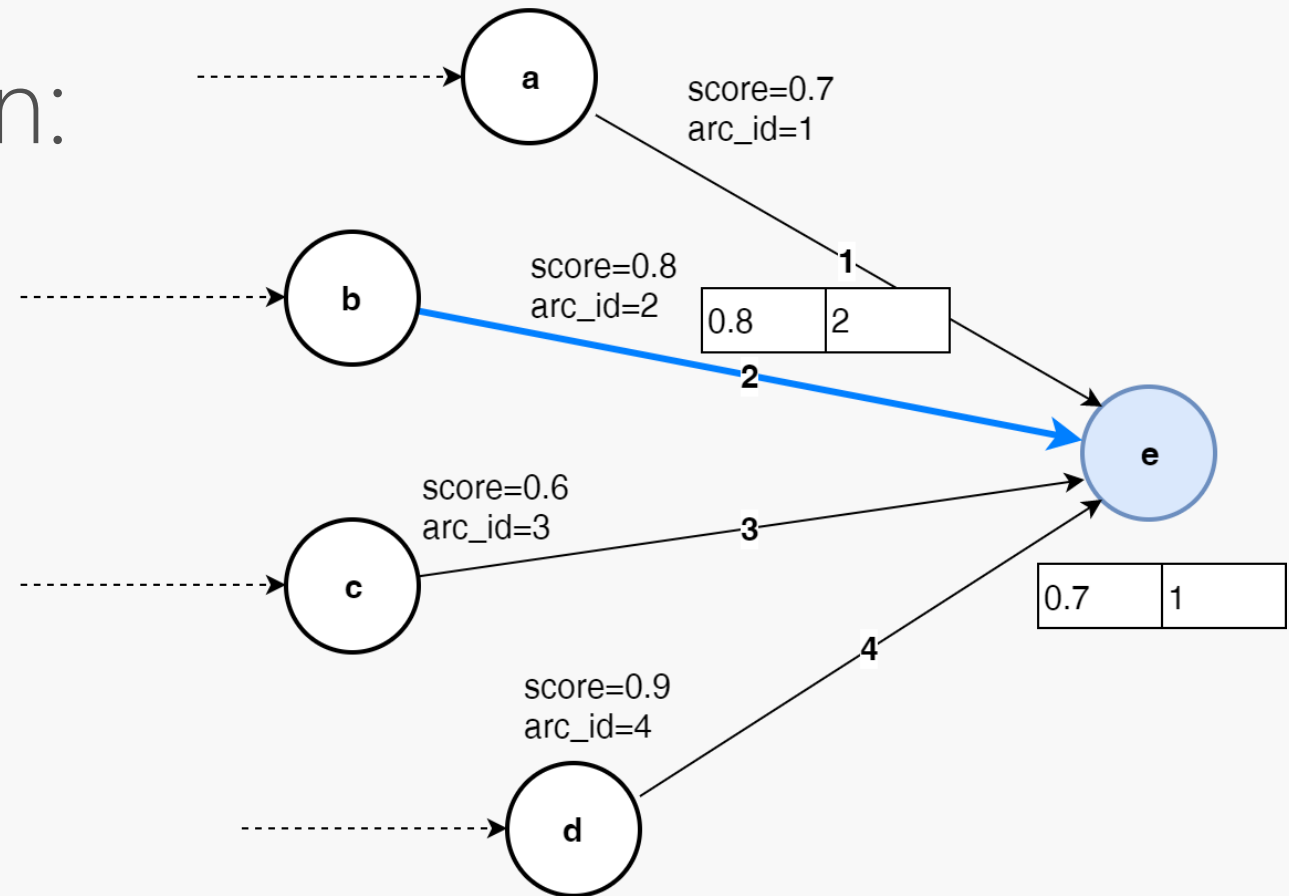


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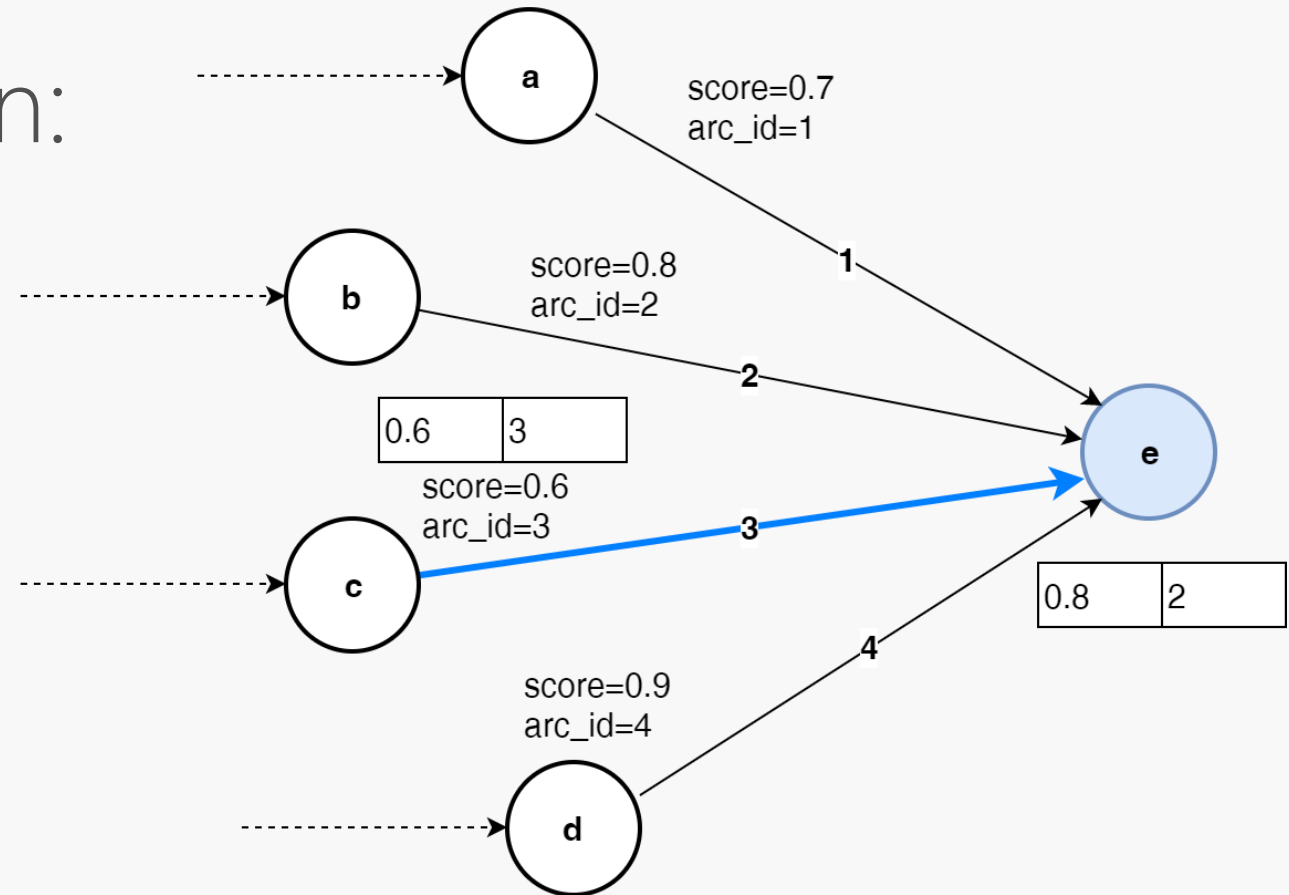


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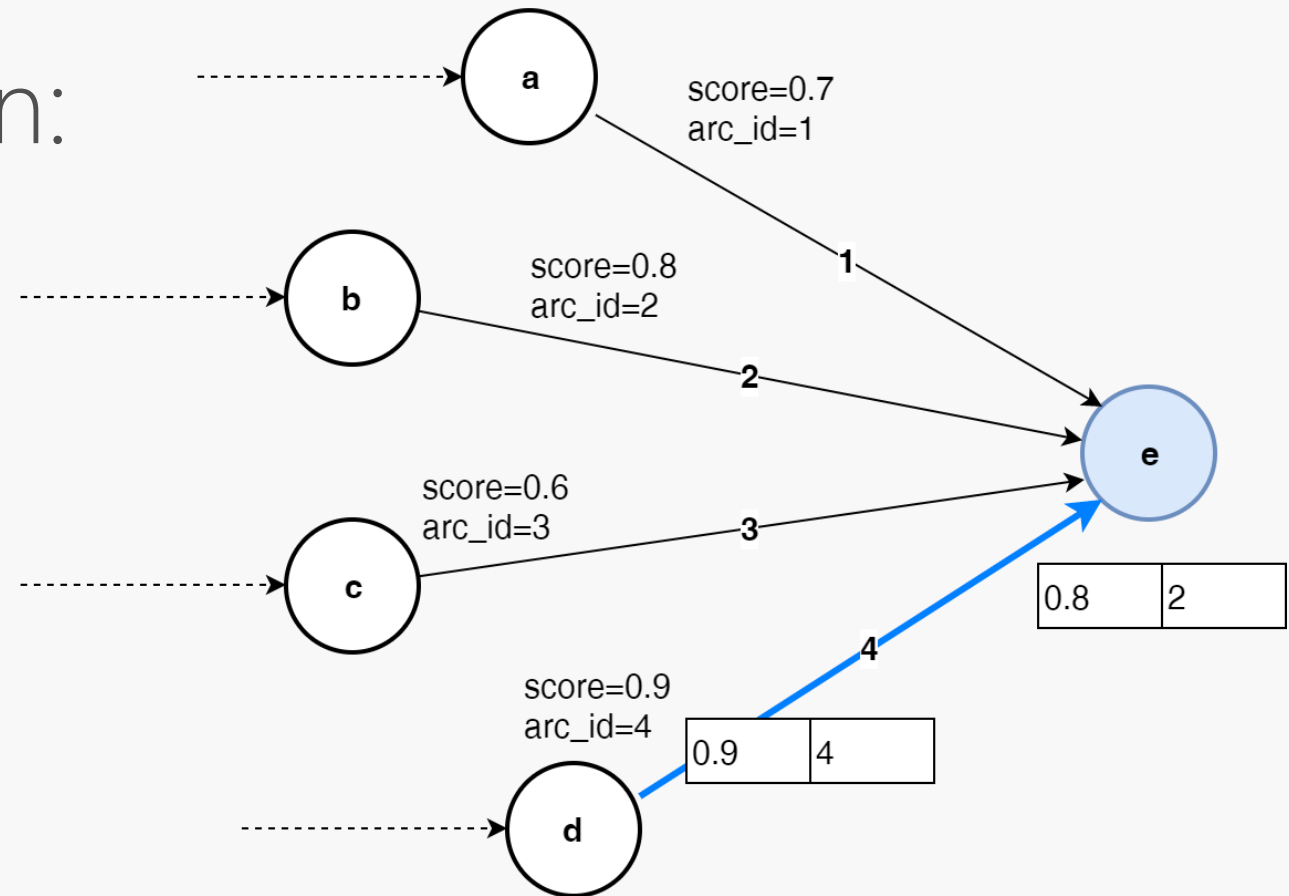


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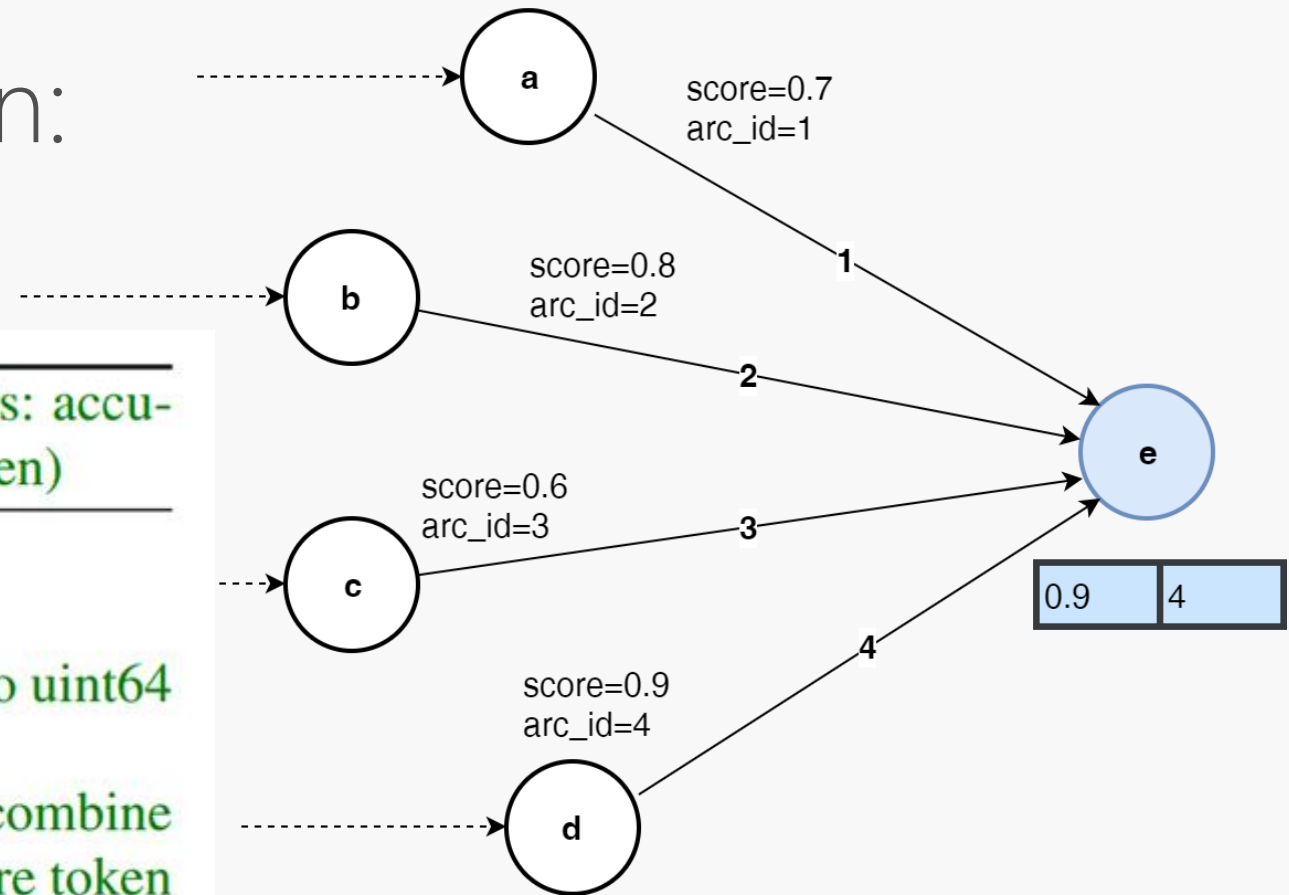
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# Token recombination

- Proposed implementation:
  - Single atomic operation<sup>1</sup>

**Algorithm 1** Thread-level Token Recombination (Inputs: accumulated cost, an out-going WFST arc and a current token)

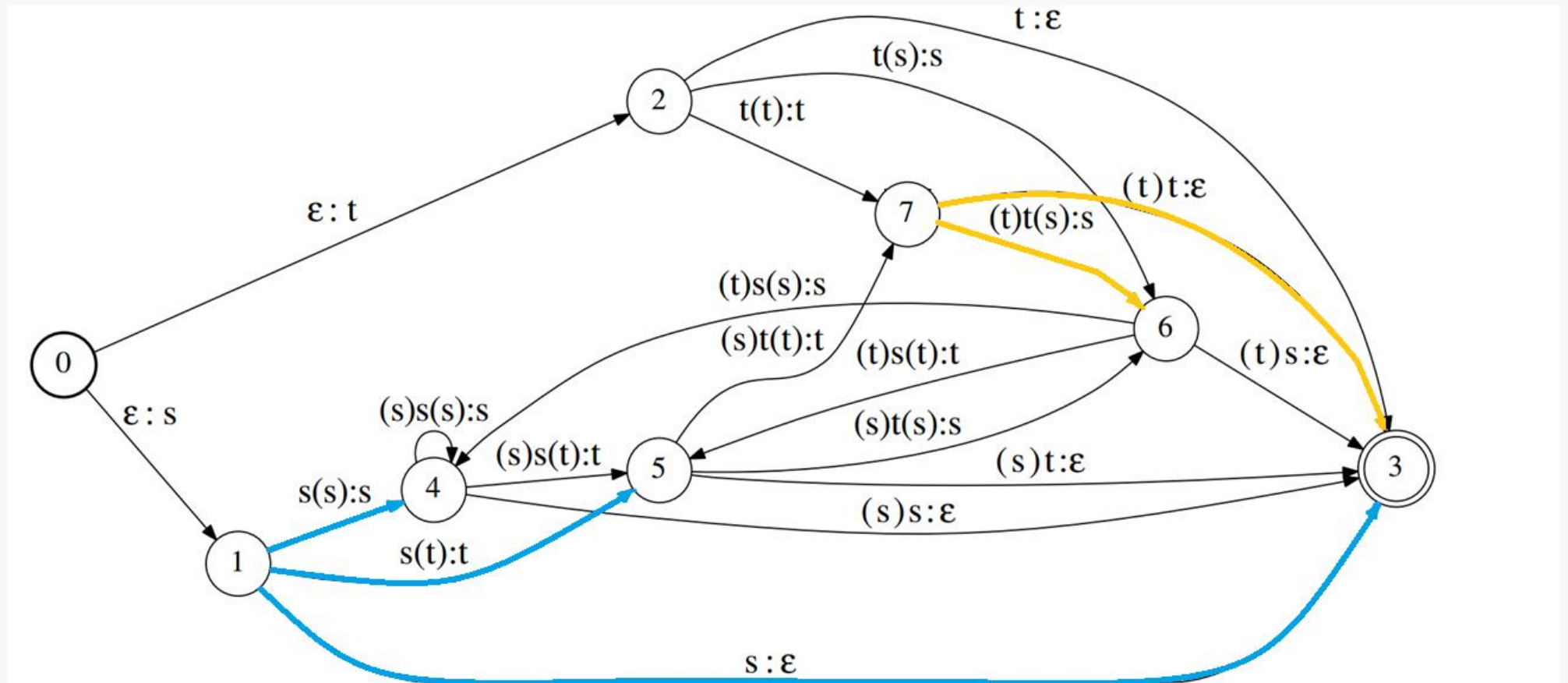
```
1: procedure RECOMBINE(cost, arc, curTok)
2:   oldTokPack = state2tokPack[arc.next_state]
3:   curTokPack = packFunc(cost, arc.id) ▷ pack into uint64
4:   ret = atomicMin (oldTokPack, curTokPack)
5:   if ret > curTokPack then           ▷ recombine
6:     perArcTokBuf[arc.id] = *curTok     ▷ store token
```



1. *atomicMax(\*address, val)*. Computes  $\max(*address, val)$ , writes the result to *address*, and returns the original *\*address*.

## 2<sup>nd</sup> Problem: Load balancing

- Load imbalance: different num. of out-going arcs



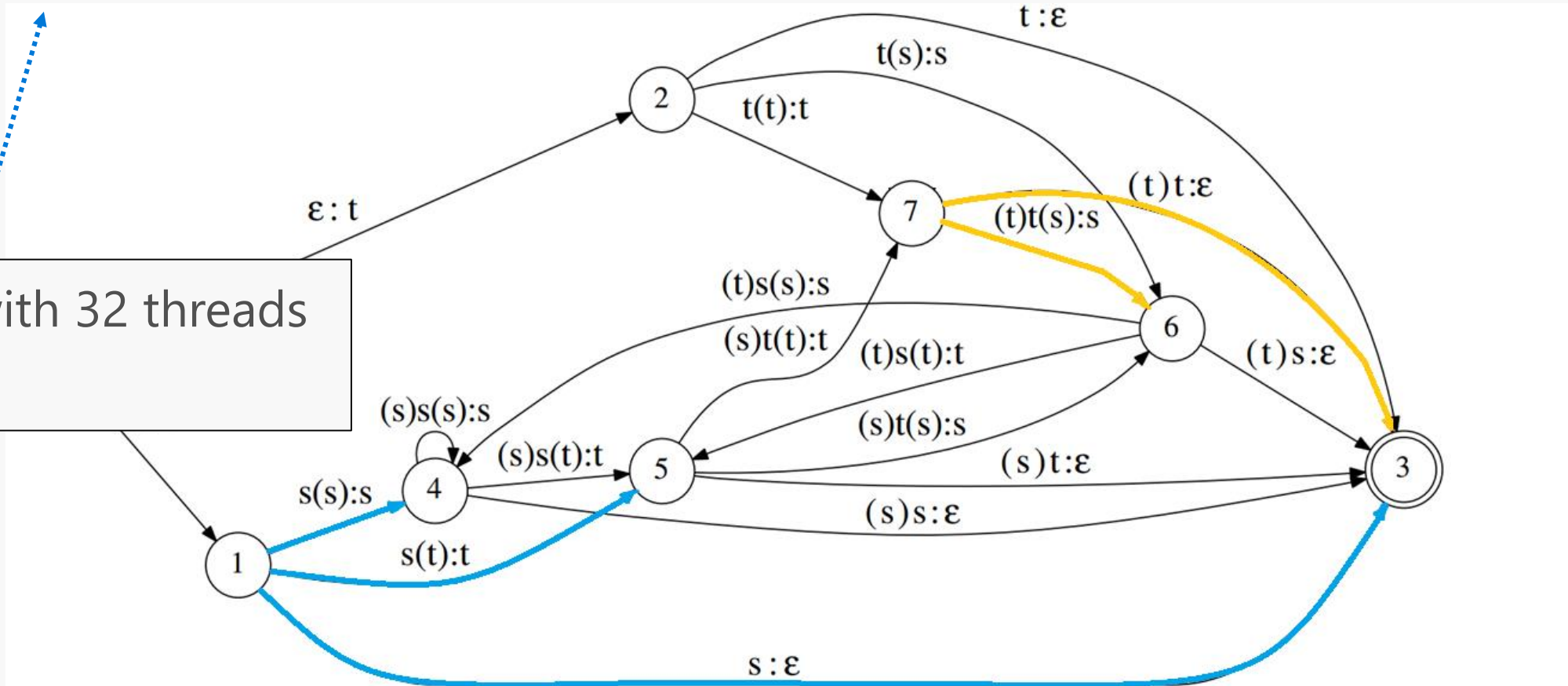
# Load balancing

Group 0 with 32 threads  
**Token ?**

*Dispatcher*

```
idx=atomicAdd(global_d,1)
```

Group 1 with 32 threads  
**Token ?**





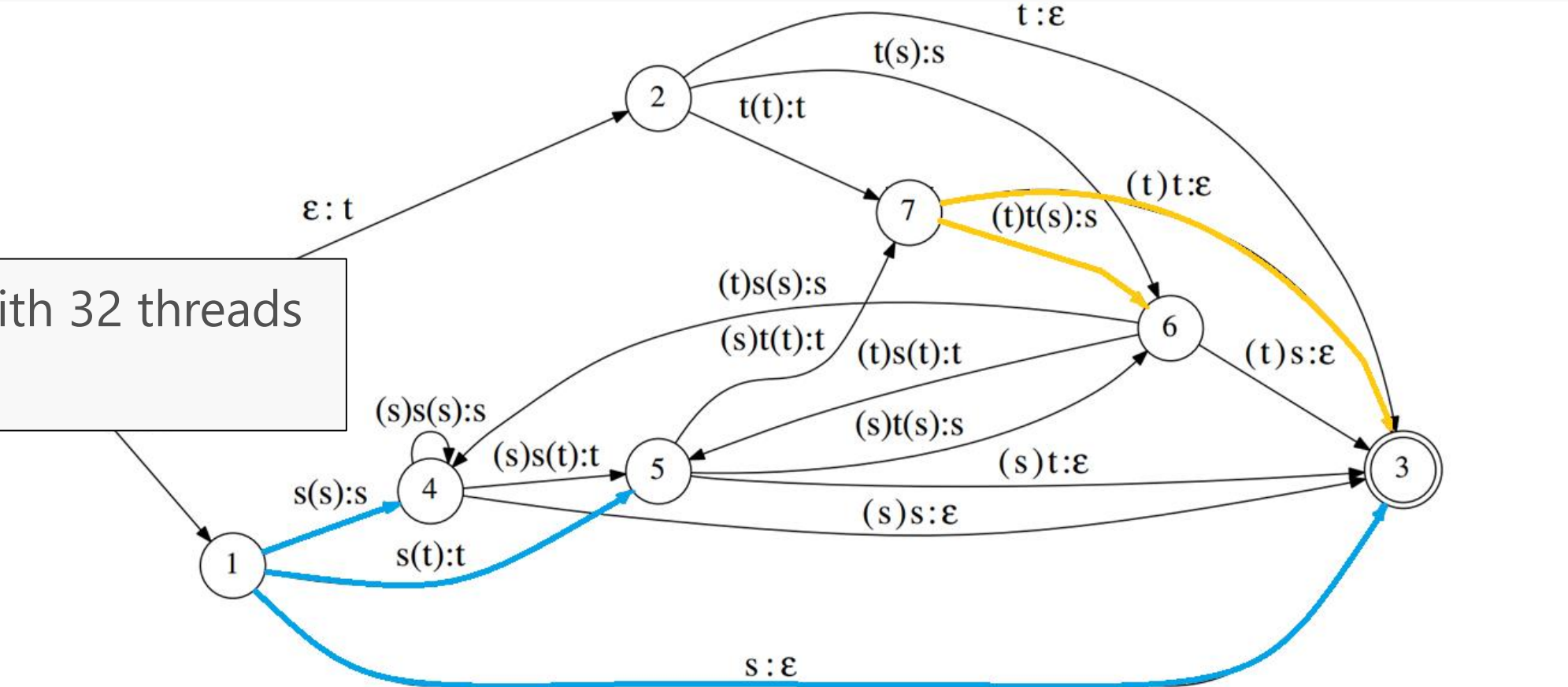
# Load balancing

Group 0 with 32 threads  
**Token 0 in State 2**

*Dispatcher*

```
idx=atomicAdd(global_d,1)
```

Group 1 with 32 threads  
**Token ?**



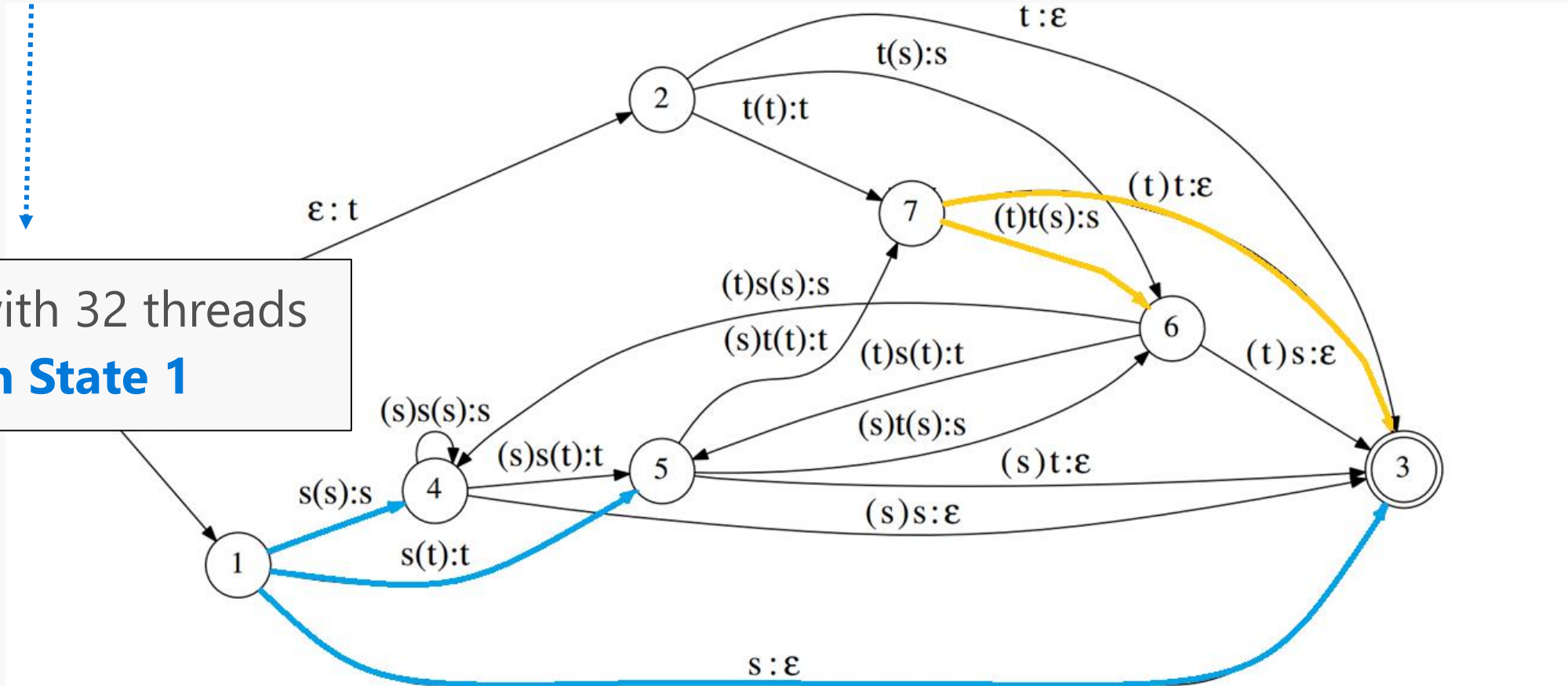
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```
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```

Group 1 with 32 threads  
**Token 1 in State 1**



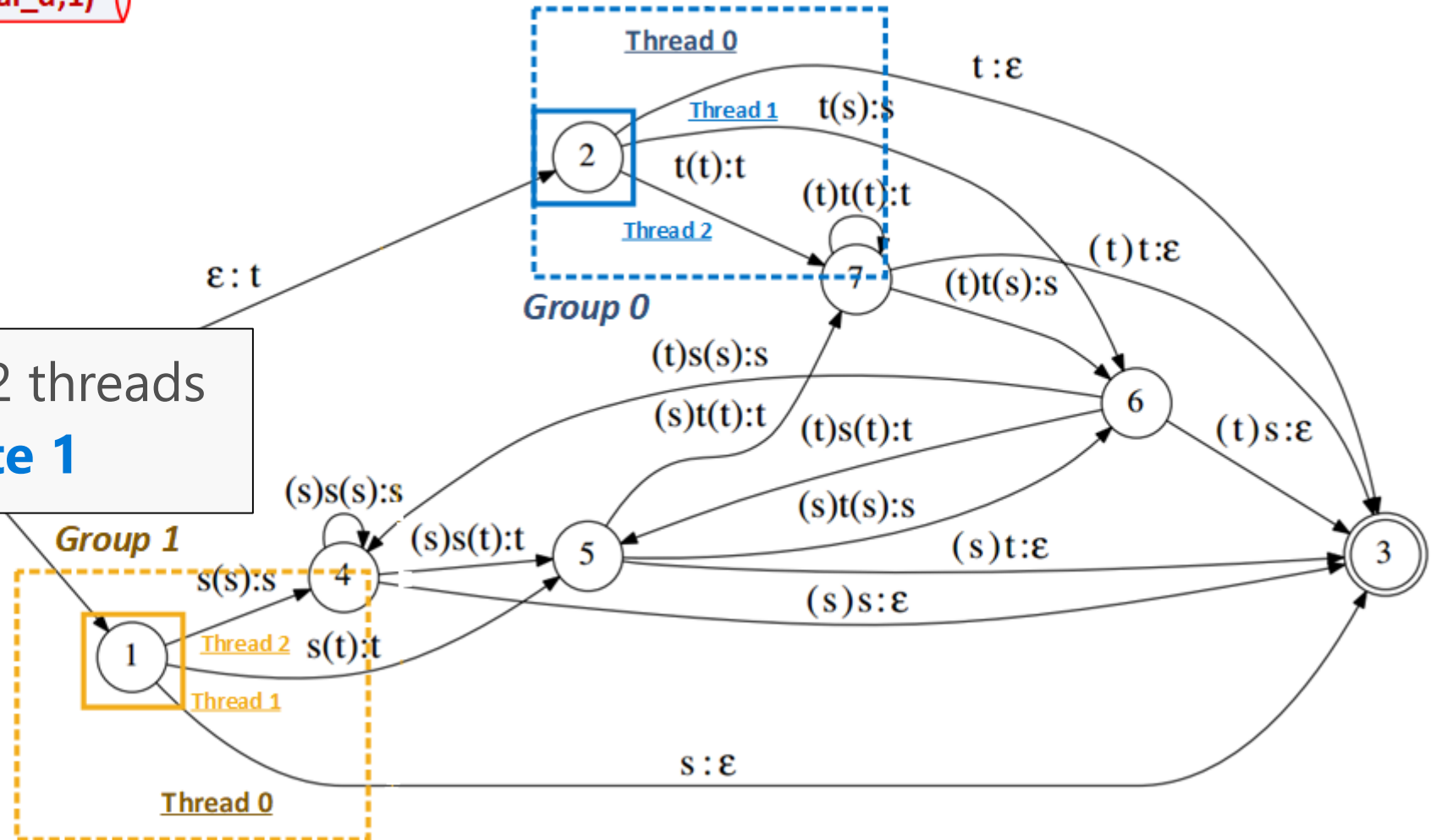
# Load balancing

Group 0 with 32 threads  
**Token 0 in State 2**

*Dispatcher*

`idx=atomicAdd(global_d,1)`

Group 1 with 32 threads  
**Token 1 in State 1**



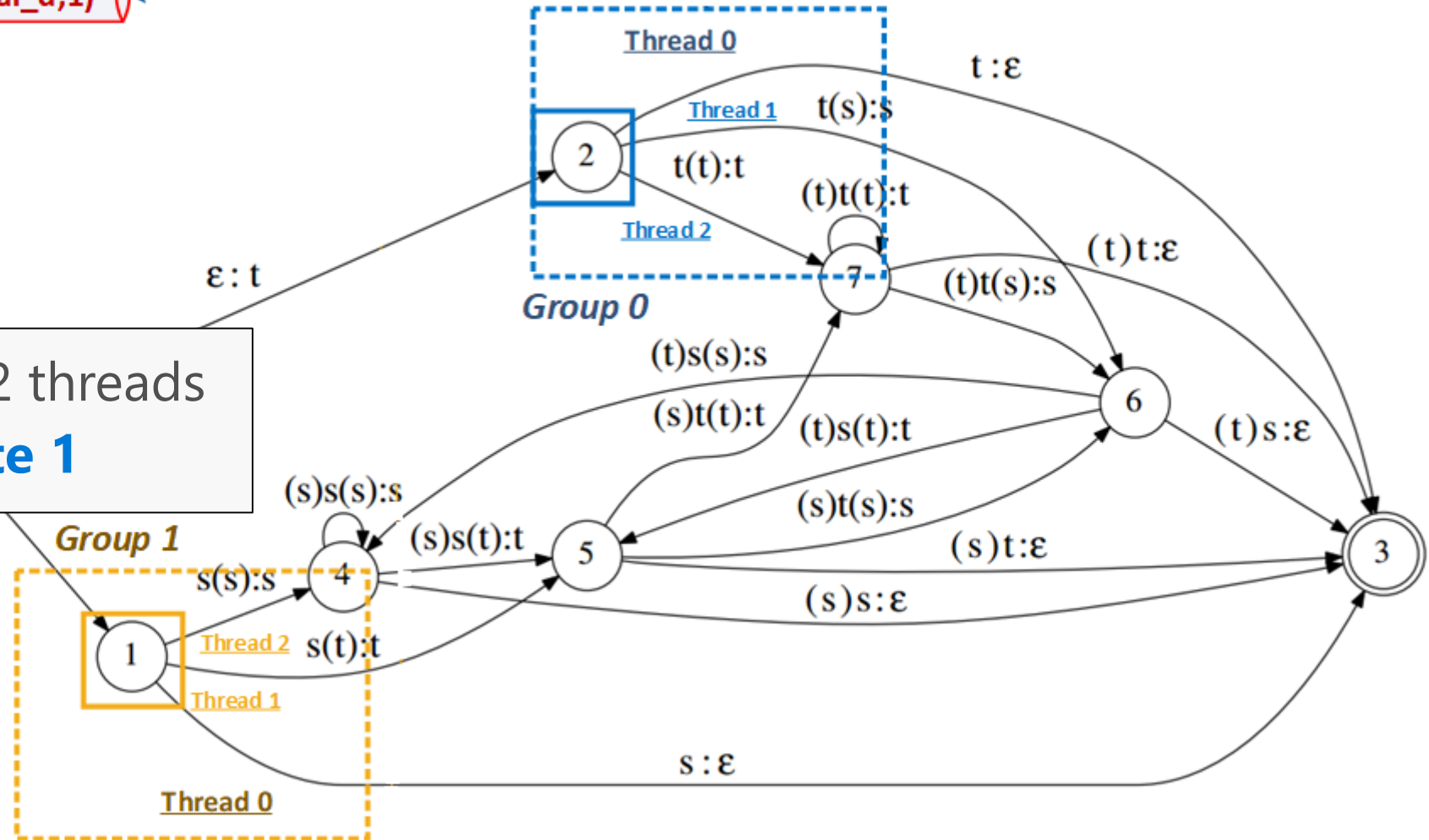
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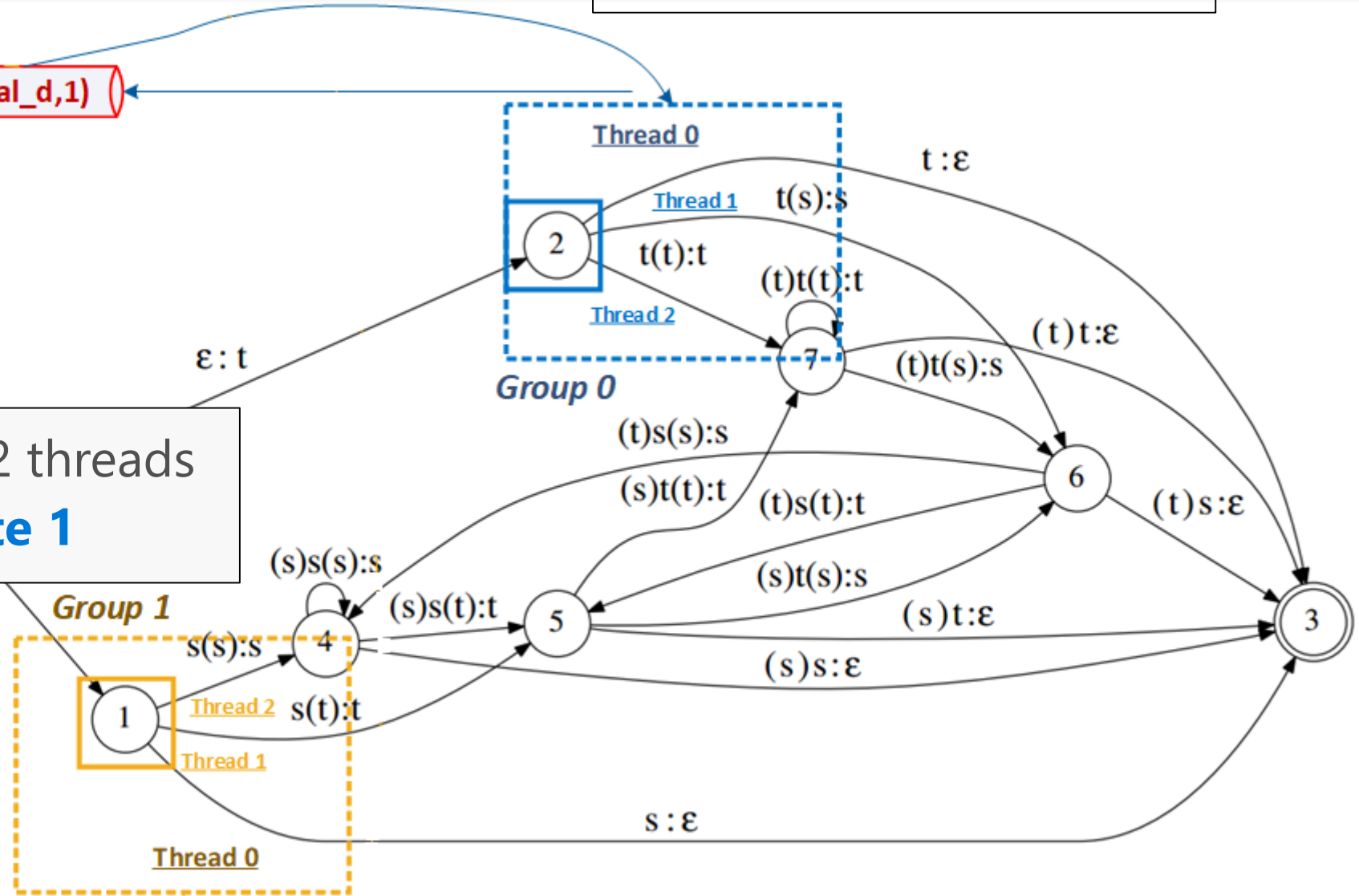
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Group 0 with 32 threads  
**Token ?**

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Group 1 with 32 threads  
**Token 1 in State 1**



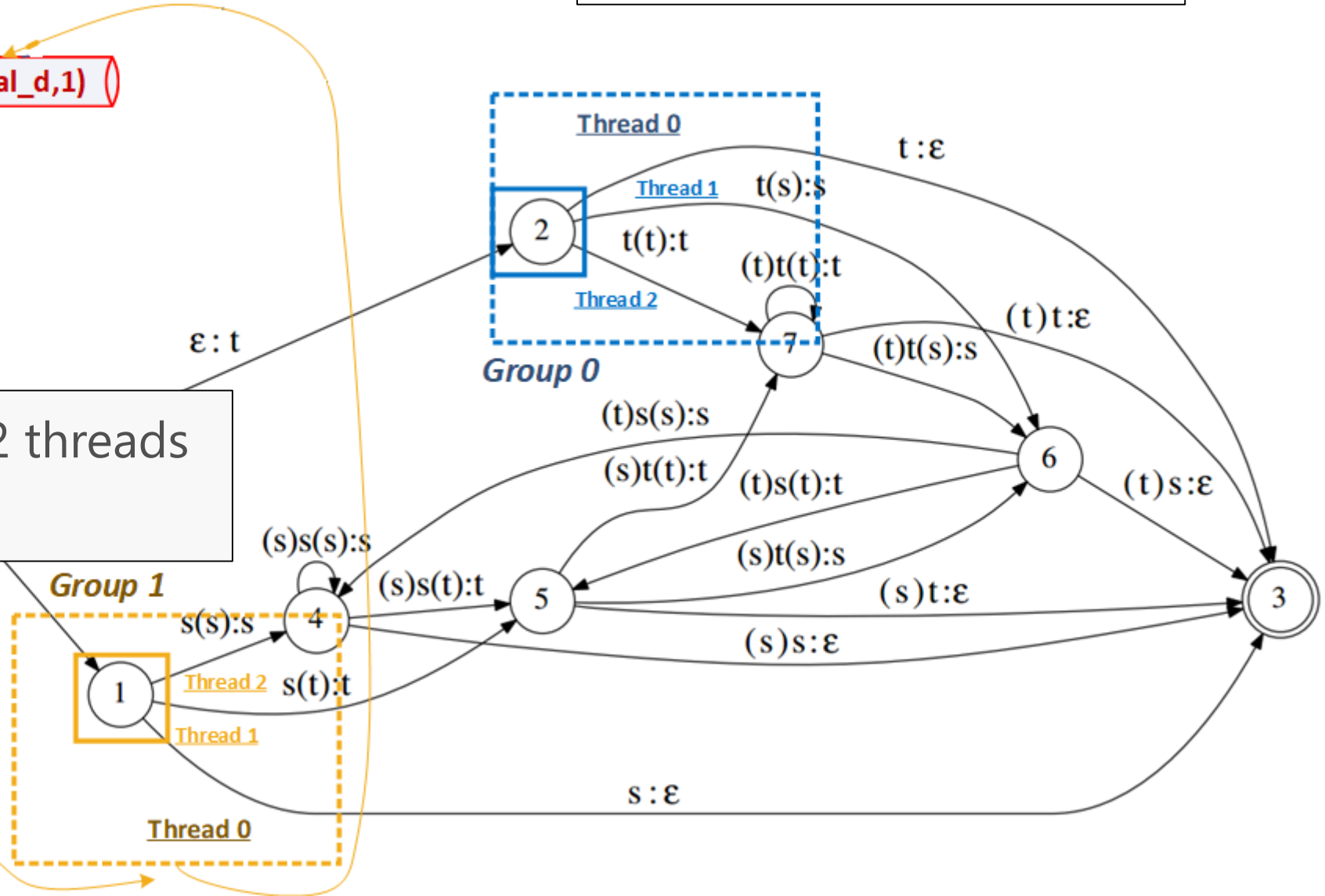
# Load balancing

Group 0 with 32 threads  
**Token 0 in State 2**

*Dispatcher*

`idx=atomicAdd(global_d,1)`

Group 1 with 32 threads  
**Token ?**



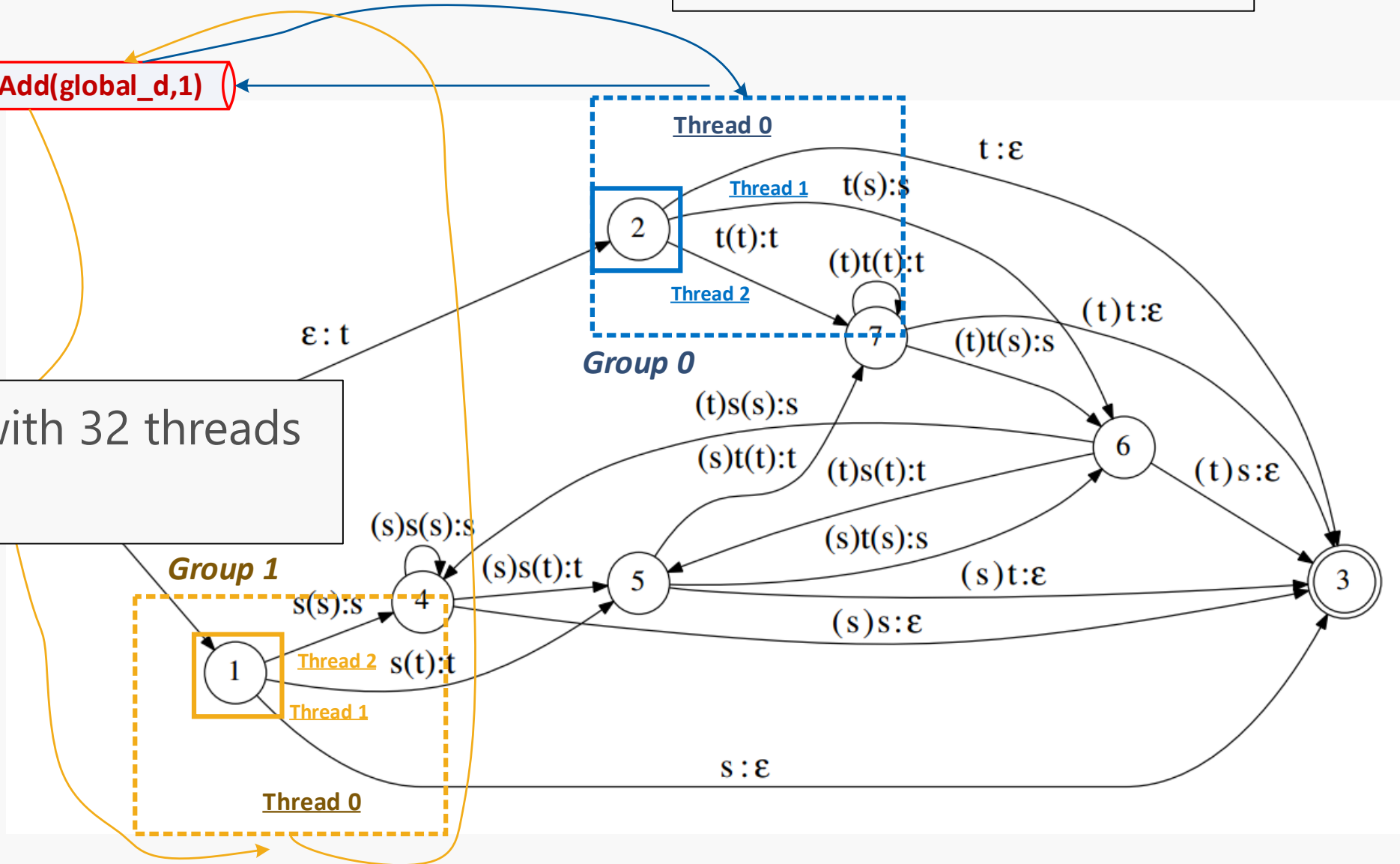
# Load balancing

Group 0 with 32 threads  
**Token ?**

*Dispatcher*

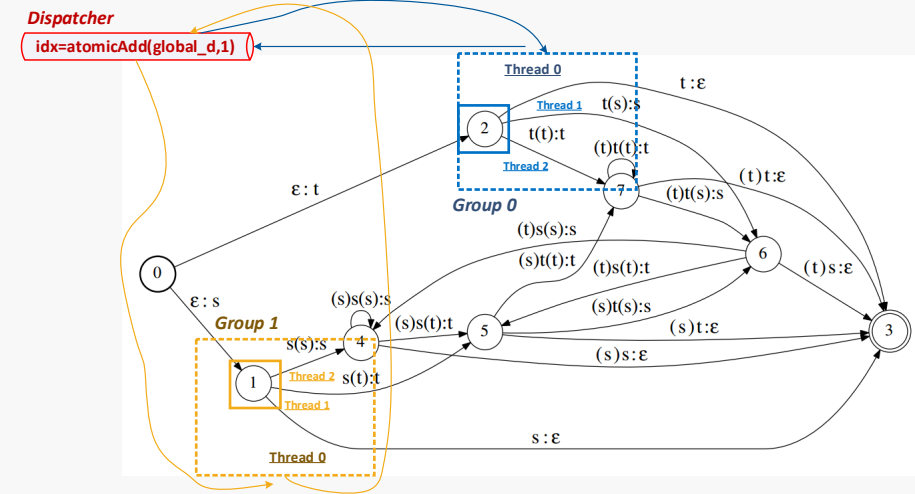
`idx=atomicAdd(global_d,1)`

Group 1 with 32 threads  
**Token ?**



# Load balancing

- Dynamic load balancing



---

**Algorithm 2** Grid-level Token Passing ( $N=32$ ; Inputs: the current active token vector)

---

- 1: **procedure** DYNAMIC LOAD BALANCING (toks)
  - 2:     group = cooperative\_groups::tiled\_partition<32>
  - 3:     **if** group.thread\_rank()==0 **then**   ▷ rank 0 in each group
  - 4:         i = `atomicAdd(global_d,1)`   ▷ allocate new tokens
  - 5:     i = `group.shfl(i,0)`   ▷ rank 0 broadcasts i to whole group
  - 6:     **if** i >= sizeof(toks) **then** return   ▷ all tokens processed
  - 7:     **for** arc in tok2arcs(toks[i]) **do**    ▷ thread parallelism
  - 8:         **call** *Recombine*(toks[i].cost+arc.cost, arc, toks[i])
-



# 3<sup>rd</sup> Problem: Lattice processing

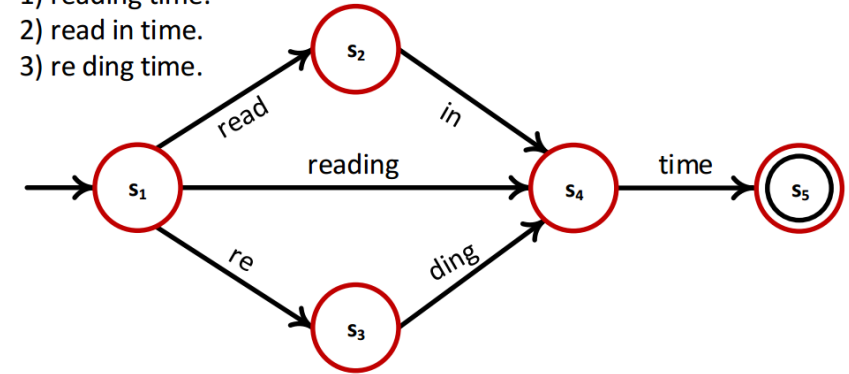
- Linkedlist → vector
- Atomic operations
  - e.g. memory allocation

```
// implementation of v.push_back(val)
int idx = atomicAdd(cnt_d, 1); // idx=cnt_d++
mem_d[idx] = *val; // store data
```

- Parallel lattice pruning

**N-best hypotheses:**

- 1) reading time.
- 2) read in time.
- 3) re ding time.



# Experiments

- Setup
  - Switchboard 300 hours corpus, Cross Entropy & LF-MMI acoustic models (AM)
  - 30k-vocabulary, several tri-gram language models (LM)
- Baseline
  - Kaldi 1-best decoder
  - Kaldi lattice decoder
- GPU Optimization<sup>1</sup>
  - fast memcpy; merge GPU kernels by adding grid sync.; etc. (rel. 20% speedup)

---

1. <https://github.com/chenzhehuai/kaldi/tree/gpu-decoder>

# Experiments

- Performance

Table 1: *1-best and Lattice Performance (beam=14).*

system	<i>lat. den.</i>		WER	<i>+rescored</i>	OWER		NCE
CPU	30.3		15.5	14.3	11.2		0.322
GPU	30.2		15.5	14.3	11.2		0.328

- The same 1-best & lattice quality

# Experiments

- Speedup

Table 2: *Speedup of the Proposed Method (beam=14).*

system	1-best		+ lattice	
	RTF	$\Delta$	RTF	$\Delta$
CPU	<b>0.16</b>	<b>1.0X</b>	<b>0.27</b>	<b>1.0X</b>
+ 8-sequence (1 socket)	-	-	0.15	1.8X
GPU	0.016	10X	0.080	3.3X
+ atomic operation	0.015	11X	0.077	3.5X
+ dyn. load balancing	<b>0.011</b>	<b>15X</b>	0.075	3.6X
+ lattice prune	-	-	<b>0.028</b>	<b>9.7X</b>
+ 8-sequence (MPS)	0.0035	46X	0.0080	34X

10X speedup

# Experiments

- Speedup

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- Speedup

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+ 8-sequence (MPS)	0.0035	46X	0.0080	34X

Improvement on naïve  
GPU decoder

# Experiments

- Speedup

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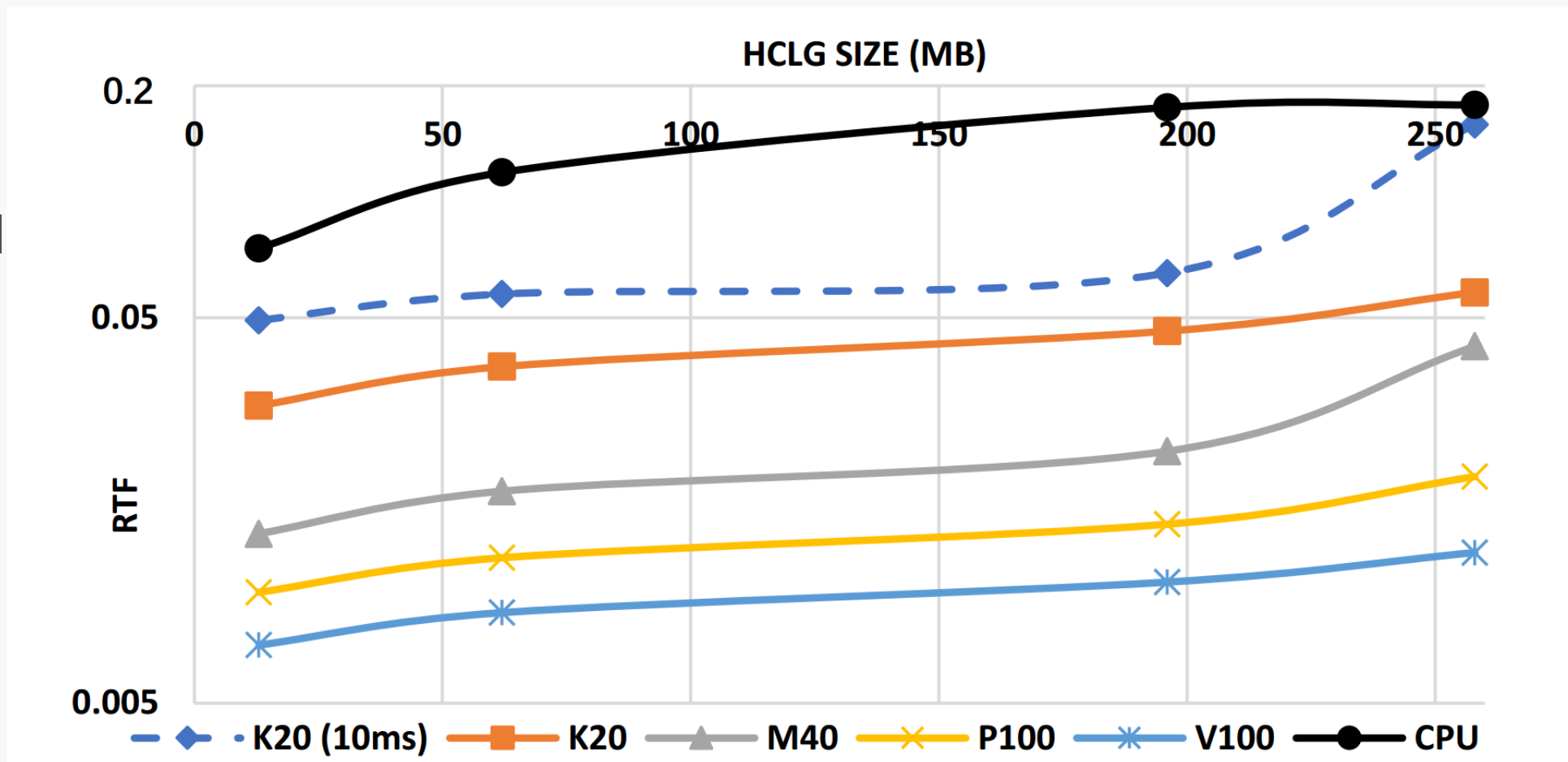
Our new number<sup>1</sup>  
is over **50X**

1. <https://github.com/chenzhehuai/kaldi/tree/gpu-decoder>



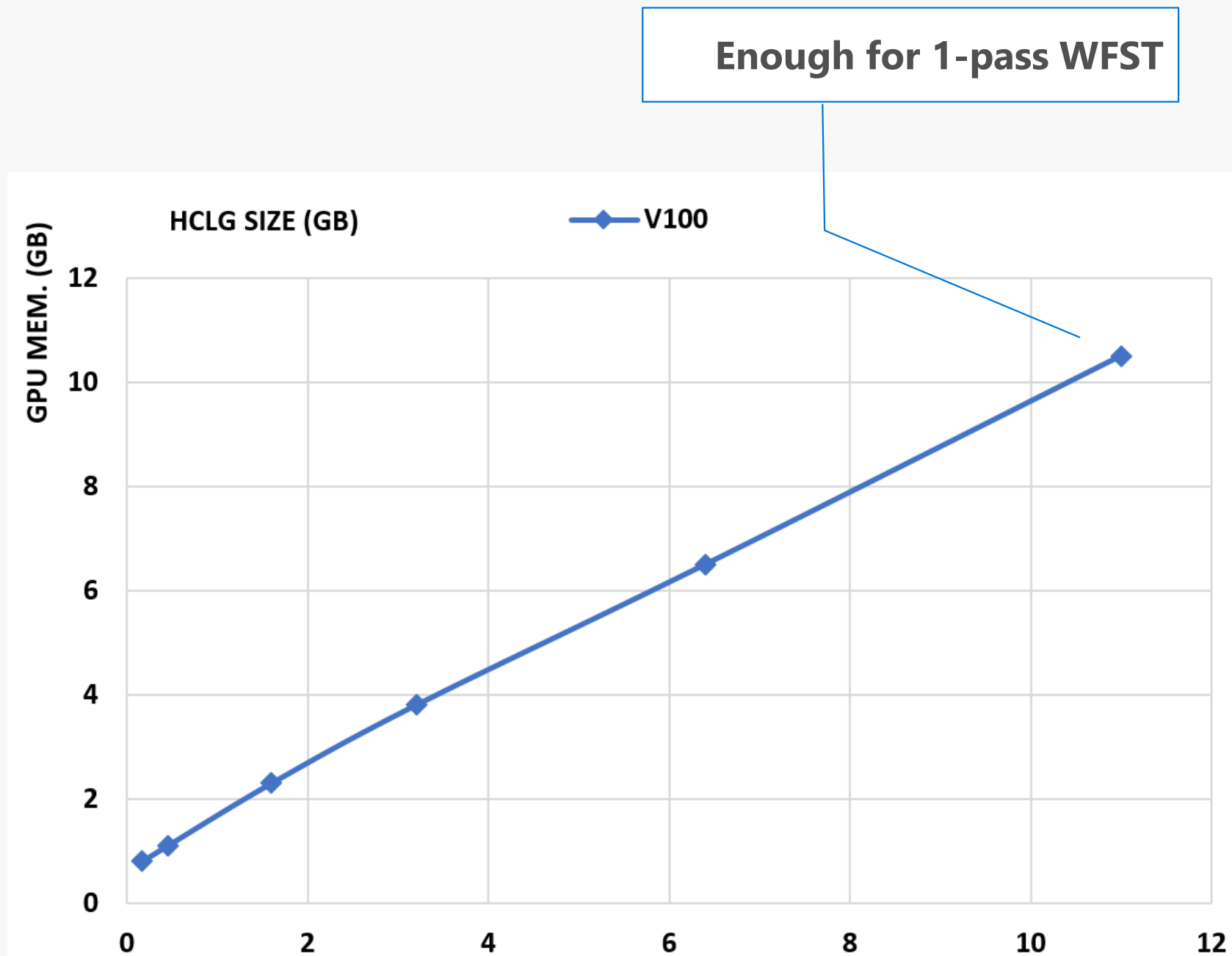
# Experiments

- Compatibility
  - GPU arch.
  - WFST size
  - Acoustic model



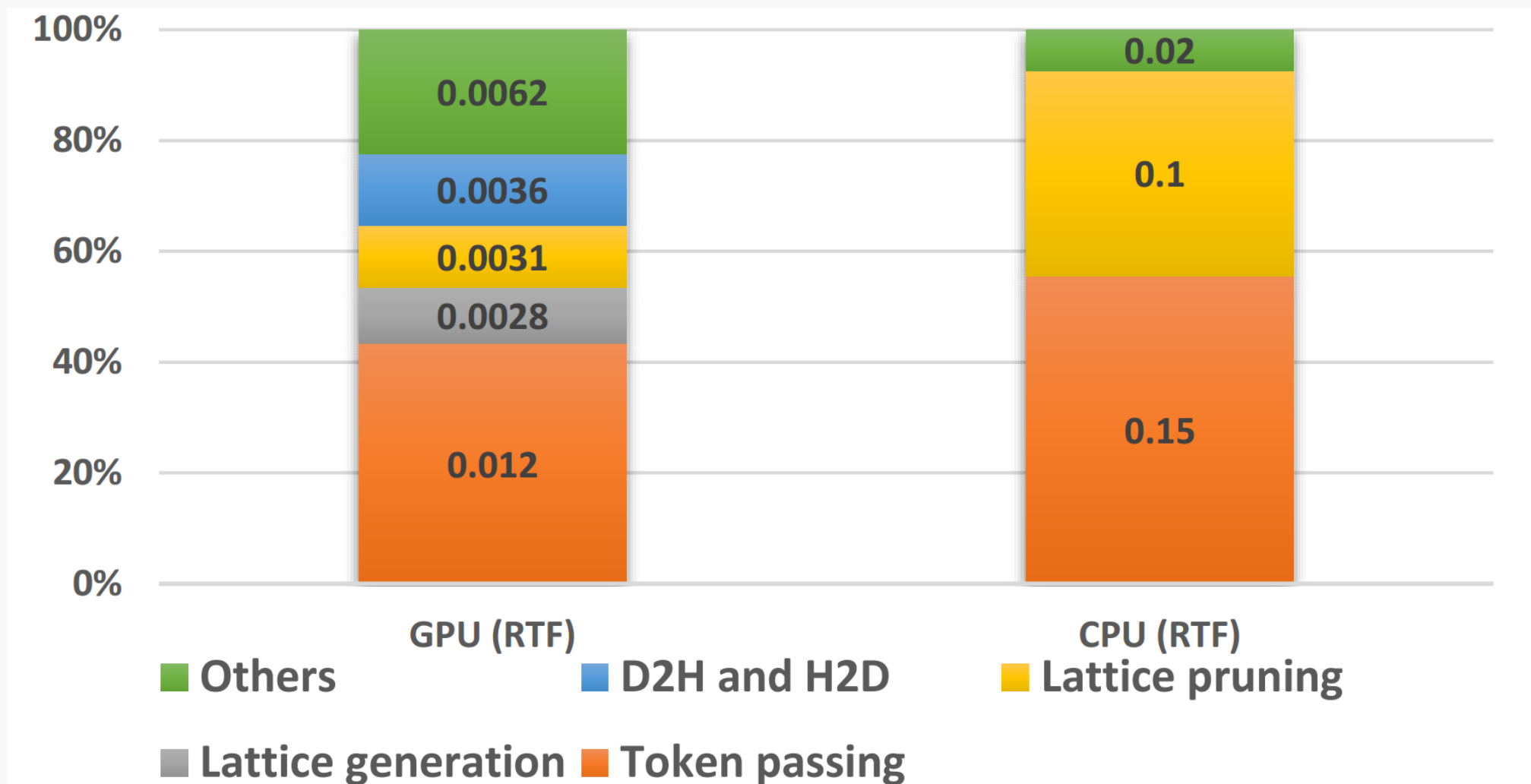
# Experiments

- GPU Memory v.s. WFST size



# Experiments

- Profiling



# Conclusion & Future works

- Propose:
  - parallel Viterbi decoding & lattice processing
- Implementation:
  - Open-source & compatible with Kaldi recipes:  
<https://github.com/chenzhehuai/kaldi/tree/gpu-decoder>
- Future works:
  - More researches in GPU decoding
  - WFST algorithms, e.g. compose, determinize and minimize
  - Tight integration with acoustic inference (in GPUs)

Backup materials

# Lattice processing

- Lattice pruning
  - The original CPU version: iteratively updates extra costs of nodes and arcs until they stop changing
- Proposed:
  - updating in parallel
  - Linkedlist → vector
  - Atomic operations

---

**Algorithm 3** Grid-level Lattice Processing (processing frame, lattice token vector and lattice arc vector are taken as inputs)

---

```
1: procedure PRUNE LATTICE FOR FRAME (f, toks, arcs)
2:   for tok in toks(f-1) do           ▷ extraCost initialization
3:     tok.extraCost = FLT_MAX
4:   while modified == 1 do
5:     modified = 0
6:     for arc in arcs(f) do           ▷ thread parallelism
7:       cost = ArcExtraCost(arc)
8:       ▷ returns the cost difference between the best
          path including the arc, and the best overall path.
9:       if cost < latticeBeam then
10:        atomicMin(tok.extraCost, cost)
11:        atomicAdd(modified, 1)
```

---

# Speed and memory optimization

- share WFST between utterances in a GPU
- reduce context switching overheads: multi-process service (MPS)
- Lazy malloc to reduce memory: CudaMallocManaged
- grid sync implementation

```
__syncthreads();
if (threadIdx.x == 0) {
    int nb = 1;
    if (blockIdx.x == 0) {
        nb = 0x80000000 - (gridDim.x-1);
    }
    int old_epoch = *fast_epoch;
    __threadfence();
    atomicAdd((int*)fast_epoch, nb);
    int cnt=0;
    while (((*fast_epoch) ^ old_epoch) >= 0) ;
}
__syncthreads();
```

# Speed and memory optimization

- reduce grid sync using multiple copy of variable
  - Do not need to make threads wait for `modified1 = false`

```
do {
    __grid_sync_nv_internal(params.barrier);

    swap(modified0,modified1);
    *modified1 = false;

    //__grid_sync_nv_internal(params.barrier);

    processNonEmittingTokens_function<32,2>(params,cutoff,size,modified0);
    __grid_sync_nv_internal(params.barrier);
} while ((*modified0)==true);
```



# Speed and memory optimization

- reduce grid sync using multiple copy of variable
- faster atomicAdd by launch-and-go

```
//idx=atomicAdd((int*)fast_epoch, nb);  
atomicAdd((int*)fast_epoch, nb);
```

- sharing atomicAdd
- fast copy

```
asm("st.global.v2.u64 [%0], {%1,%2};" :: "l"(a), "l"(src.x), "l"(src.y));
```